



Algebraic Program Analysis of Probabilistic Programs

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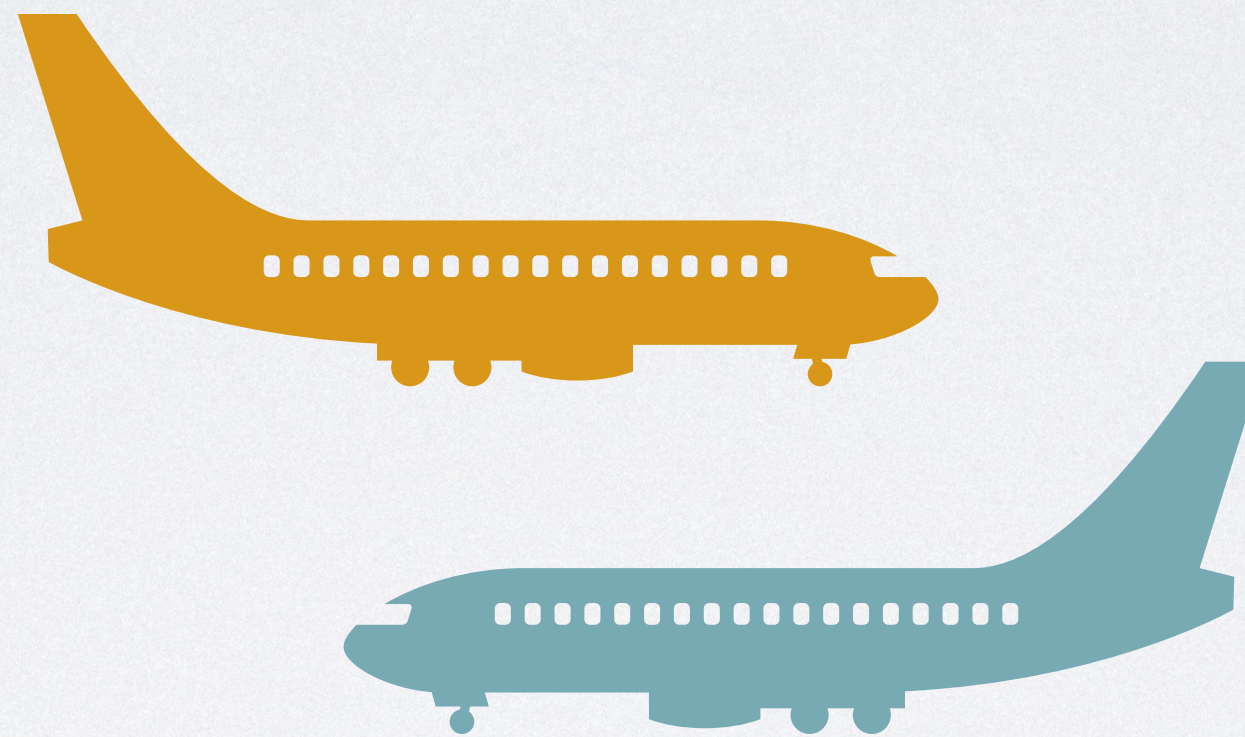
Jun 14, 2025

Joint Work with Jan Hoffmann and Thomas Reps

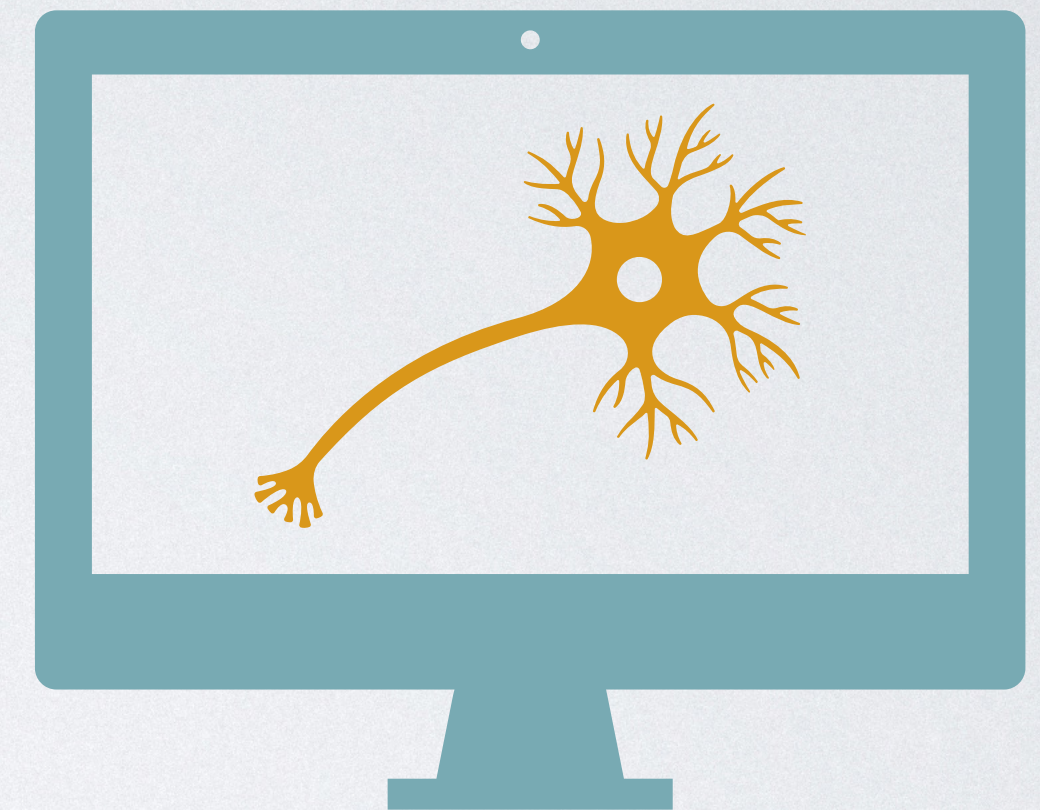
Probabilistic Systems are Becoming Pervasive



Randomized Algorithms
(improve efficiency)



Cyber-Physical Systems
(model uncertainty)



Artificial Intelligence
(describe statistical models)

Application: Randomized Quicksort

- Improve efficiency
- From $\Theta(n^2)$ to $\Theta(n \log n)$ (expected)
- Samplesort
 - Use >1 random samples as pivots

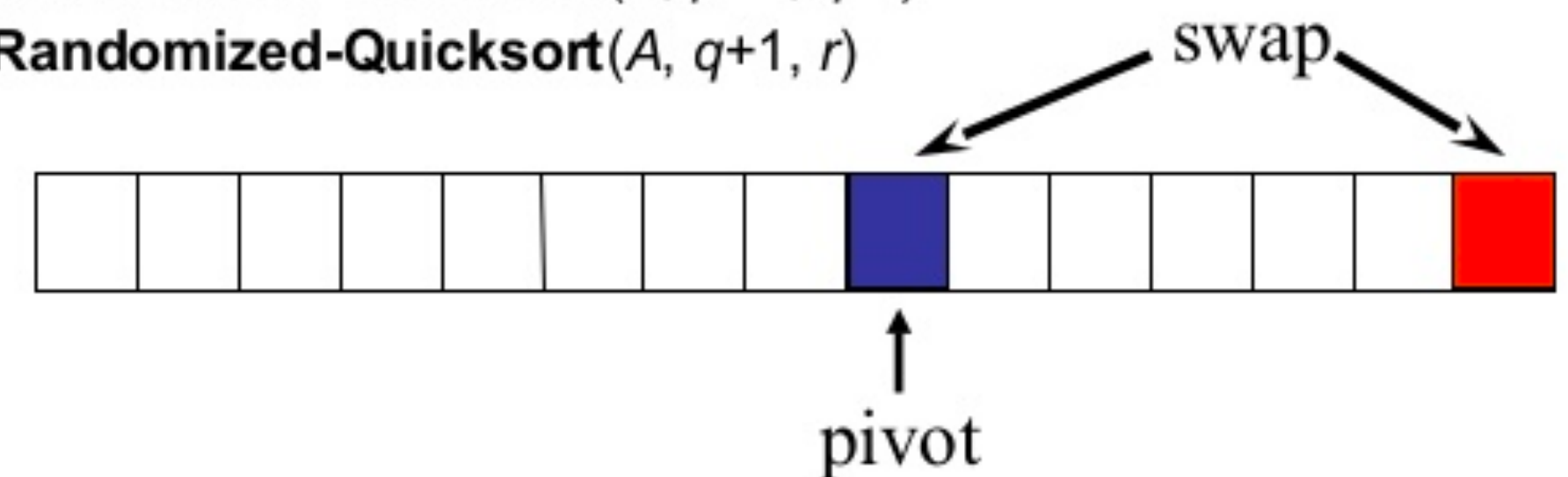
Randomized Quicksort

Randomized-Partition(A, p, r)

1. $i \leftarrow \text{Random}(p, r)$
2. exchange $A[r] \leftrightarrow A[i]$
3. **return** Partition(A, p, r)

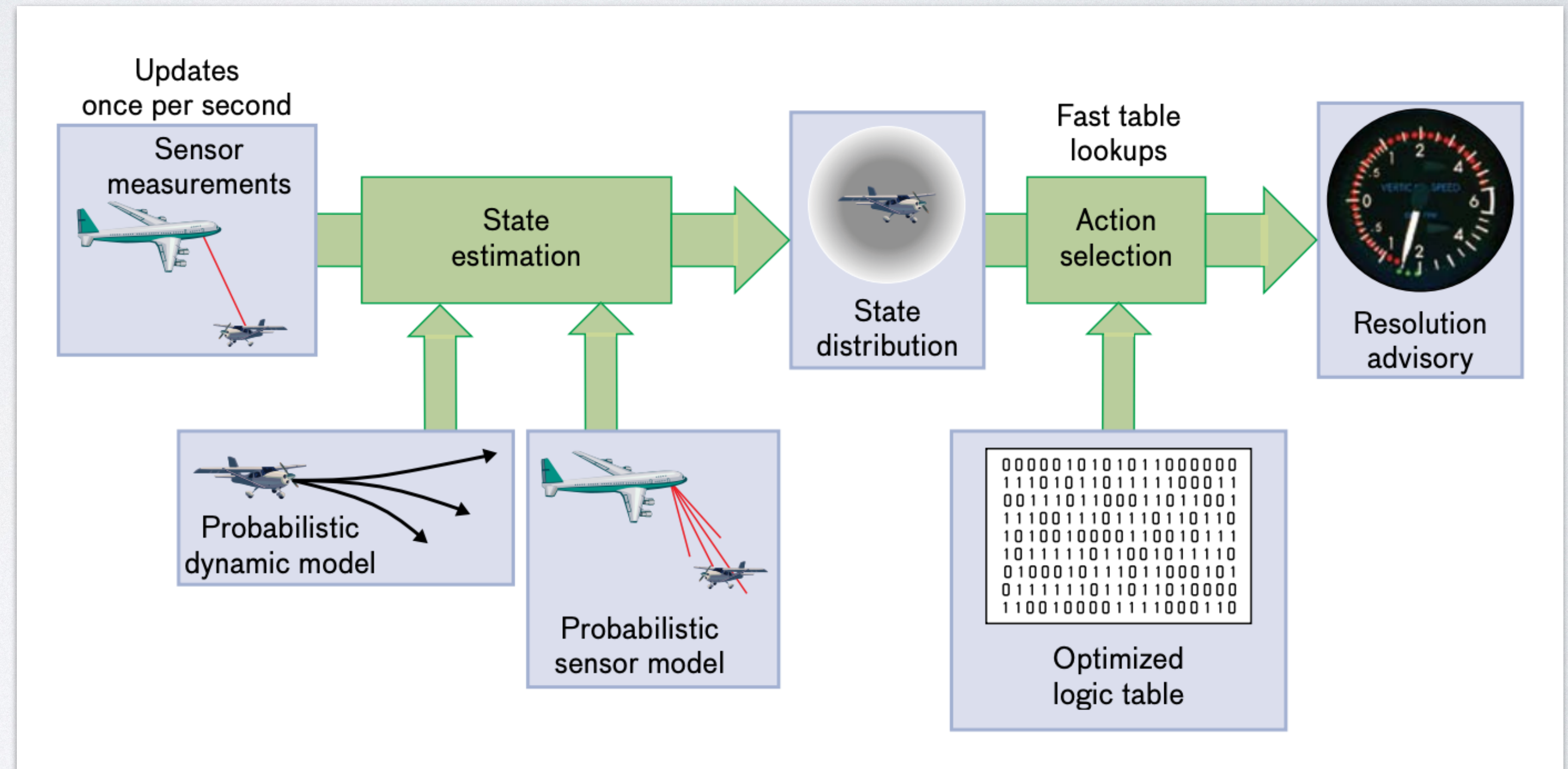
Randomized-Quicksort(A, p, r)

1. **if** $p < r$
2. **then** $q \leftarrow \text{Randomized-Partition}(A, p, r)$
3. **Randomized-Quicksort**($A, p, q-1$)
4. **Randomized-Quicksort**($A, q+1, r$)



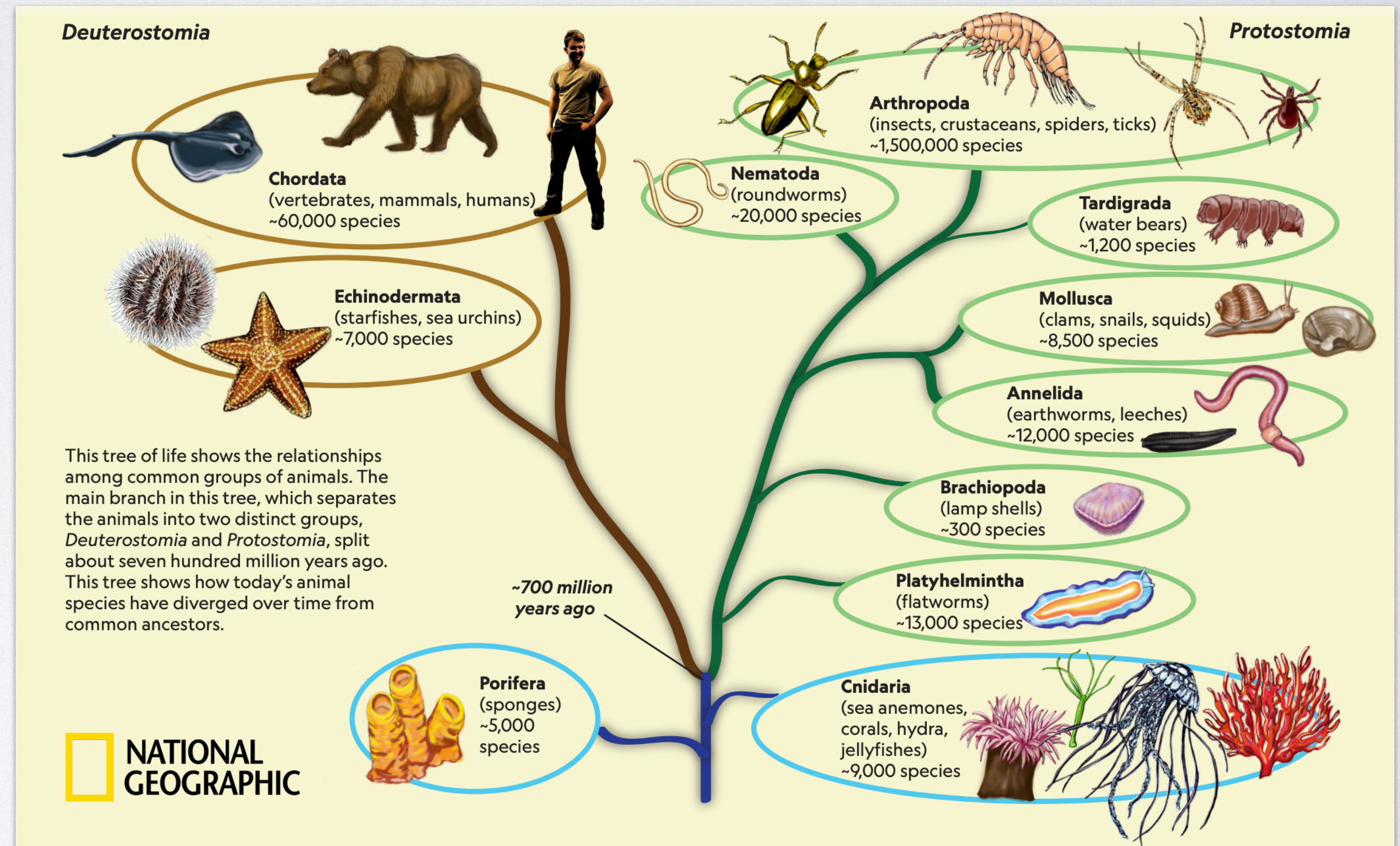
Application: Airborne Collision Avoidance

- Model uncertainty
- Probabilistic dynamics
- Probabilistic sensors
- High-confidence system



Application: Statistical Phylogenetics

- Describe statistical models
- Automated reasoning
- Apply Bayesian inference to infer evolutionary history
- Solve previously intractable problems



Ronquist, et al. "Universal probabilistic programming offers a powerful approach to statistical phylogenetics." Communications Biology (2021).

Image source: <https://www.nationalgeographic.org/media/tree-life/>.

Probabilistic Programs



Draw random **data** from distributions



Change **control-flow** at random

Probabilistic Programs

- True randomness
- A distribution on execution paths
- Probabilistic nondeterminism

```
if
| prob(1/3) → choice := 1
| prob(1/3) → choice := 2
| prob(1/3) → choice := 3
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Probabilistic Programs

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```
choice : $\in_p$  (1 @ 1/3 | 2 @ 1/3 | 3 @ 1/3)
```

Demonic Programs

- Dijkstra's **Guarded Command Language** (GCL)
- A set of execution paths
- Demonic nondeterminism

```
if
| true → prize := 1
| true → prize := 2
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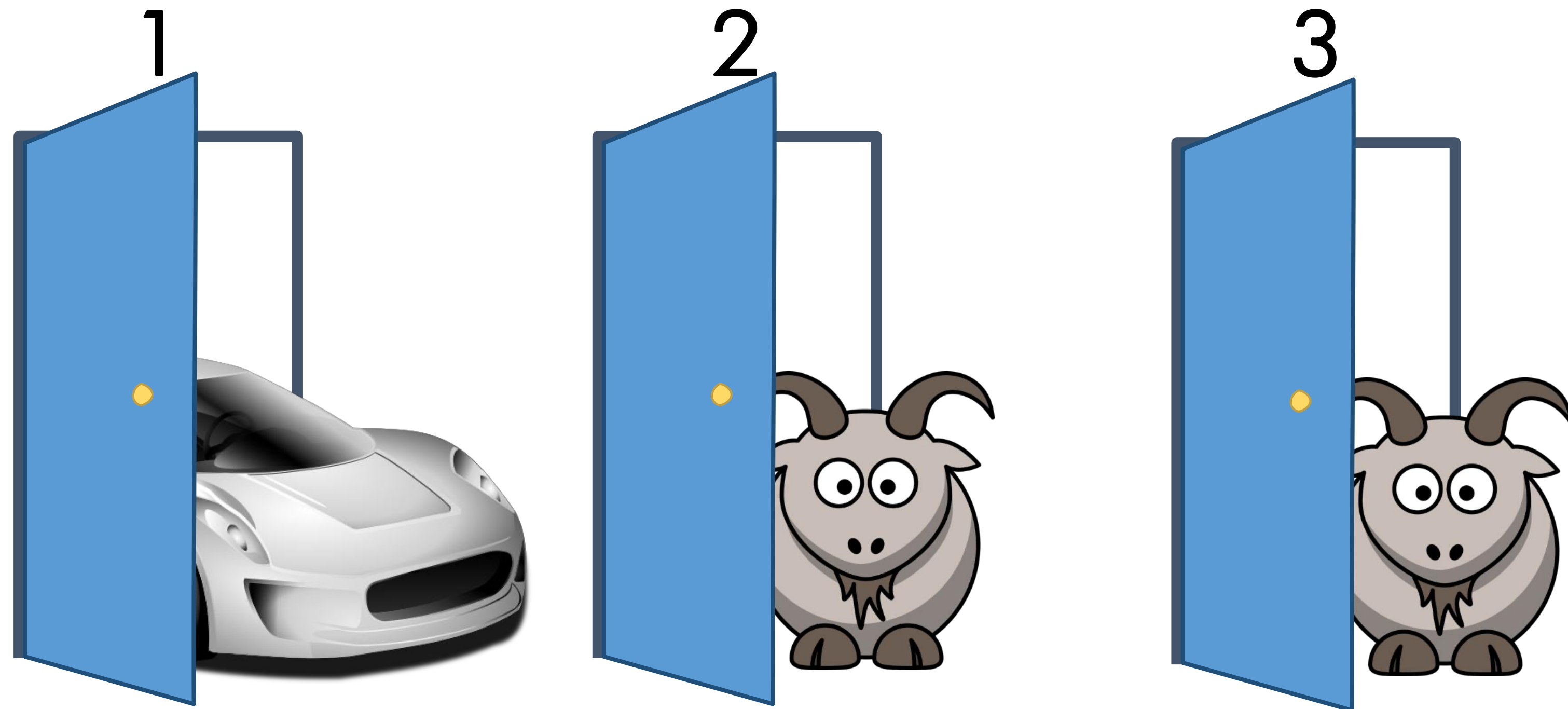
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prize $:\in_d \{1, 2, 3\}$

Example: Monty Hall





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- McIver and Morgan's **probabilistic Guarded Command Language** (pGCL)

- Combine two forms of nondeterminism:

- Probabilistic

- Demonic

```
prize : $\in_d$  {1,2,3};  
choice : $\in_p$  (1 @ 1/3 | 2 @ 1/3 | 3 @ 1/3);  
host : $\in_d$  {1,2,3} \ {prize,choice};  
if switch then  
    choice : $\in_d$  {1,2,3} \ {choice,host}  
fi
```

Example: Monty Hall

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$\mathbb{P}(\textit{choice} = \textit{prize}) = ?$

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- Demonic

- “Demons” minimize the probability

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Example: Failure Modeling

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- An example of **probabilistic modeling checking**

- Send c messages, each with a failure probability 0.1

```
fail := FALSE;  
c : $\in_d$  {0,1,2};  
while not(fail) and c > 0 do  
    fail : $\in_p$  (TRUE @ 0.1 | FALSE @ 0.9 );  
    c := c - 1  
od
```

Example: Failure Modeling

- An example of **probabilistic modeling checking**
- Send c messages, each with a failure probability 0.1
- What is the probability of success?

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Example: Abstraction

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- Program analysis introduces **abstraction**

- **Predicate Abstraction**

- $[c=0]$ is a Boolean variable

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Example: Abstraction

- Program analysis introduces **abstraction**

- Predicate Abstraction**

- $[c=0]$ is a Boolean variable

- Abstraction nondeterminism**

- Maximize $\longrightarrow$ Upper bound
 - Minimize $\longrightarrow$ Lower bound

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Examples

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What is the expected value of an expression?

How to automate such **quantitative** reasoning about probabilistic programs?

Examples

What is the probability that an assertion holds?

What is the expected value of an expression?

What is the expected time complexity of a program?

Challenge I:

How to support multiple confluence operations?

... $\vdash \in_p$...

... $\vdash \in_d$...

... $\vdash \in_a$...

Semantic Algebras

- **Kleene Algebras:** A **compositional** and **flexible** framework for program semantics

Program Construct

Algebraic Representation

A program S

An interpretation $\mathbb{S}$ of S into the algebra

Branching between A and B

$A \oplus B$

Sequencing of A and B

$A \otimes B$

Iteration (i.e., loop) of A

A^*

“abort”, “skip”

$\underline{0}, \underline{1}$



Do Kleene Algebras Suffice?

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Probabilities sum up to 2!

Our Approach: Markov Algebras

- Key observation: Probabilistic programs have **multiple confluence operations**

$$\langle M, \sqsubseteq, \otimes, {}_{\phi}\oplus, \sqcap, \underline{0}, \underline{1} \rangle$$

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form a CPO

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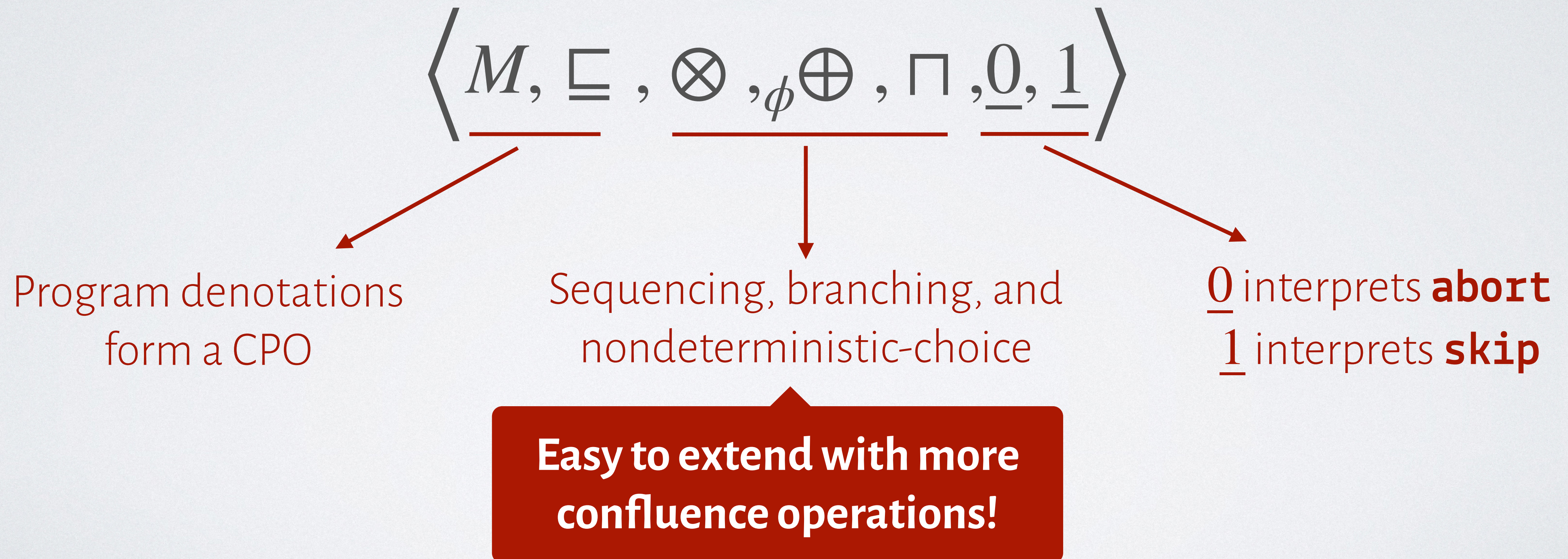
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$$\begin{aligned} (a \otimes b) \otimes c &= a \otimes (b \otimes c) \\ a \otimes \underline{1} &= \underline{1} \otimes a = a \\ a_{\phi} \oplus b &= b_{\overline{\phi}} \oplus a \\ a \sqcap a &= a \\ &\dots \end{aligned}$$



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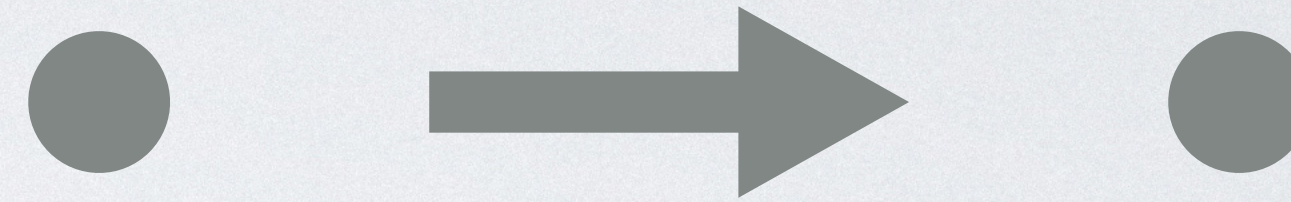
Recursive Program Scheme



Flexibility: Different Semantics

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Standard: *State* $\rightarrow$ *State*

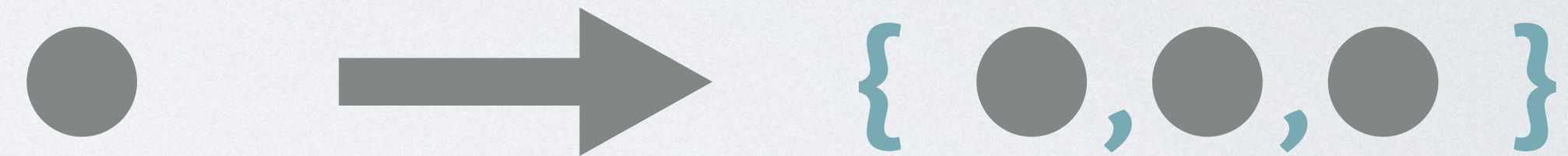


Flexibility: Different Semantics

Standard: $State \rightarrow State$



GCL: $State \rightarrow \wp(State)$

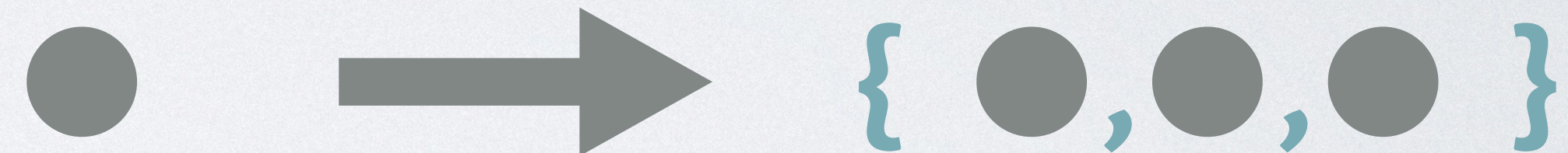


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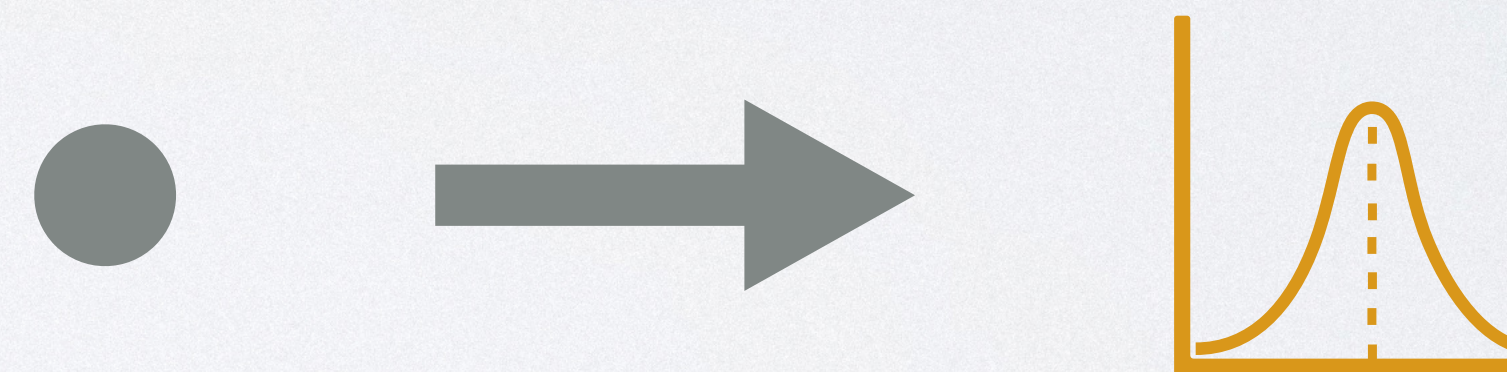
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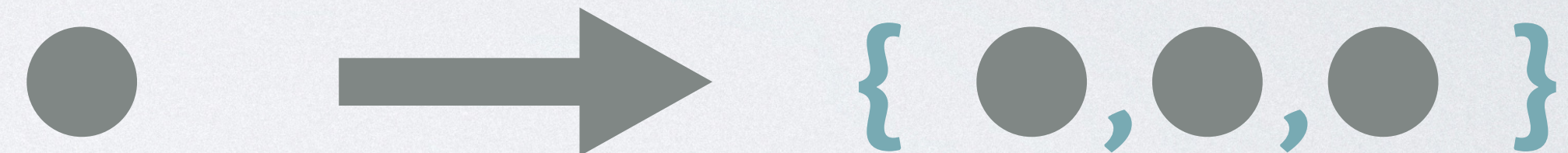


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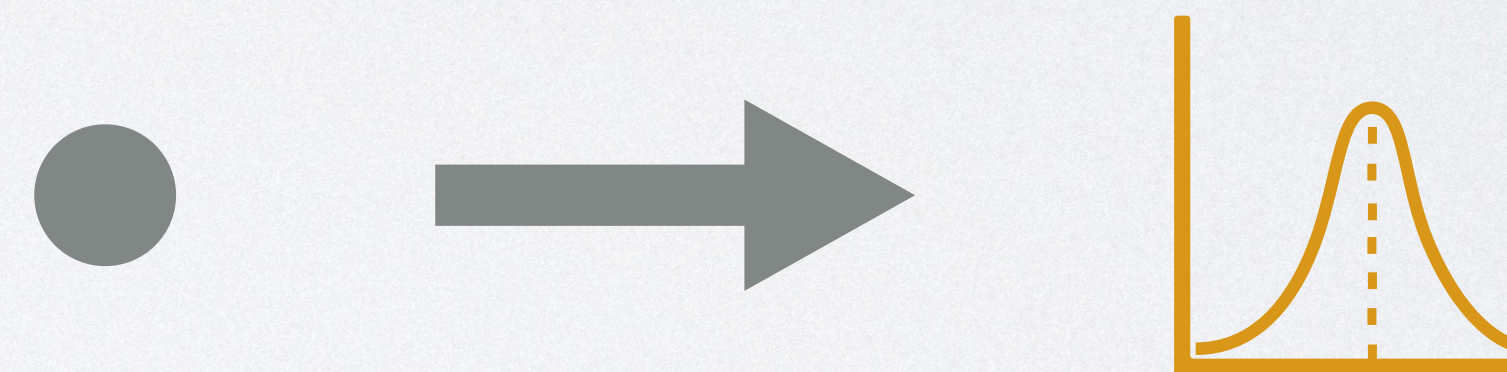
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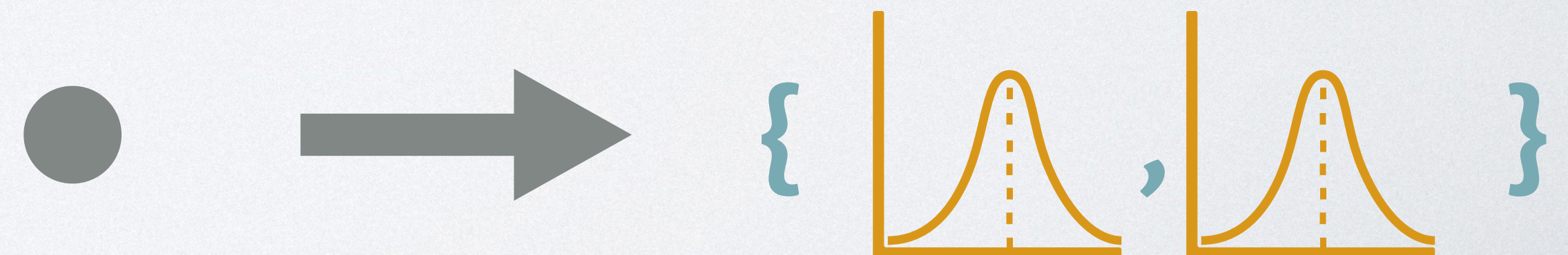
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pGCL: $State \rightarrow \wp(\mathbb{D}(State))$

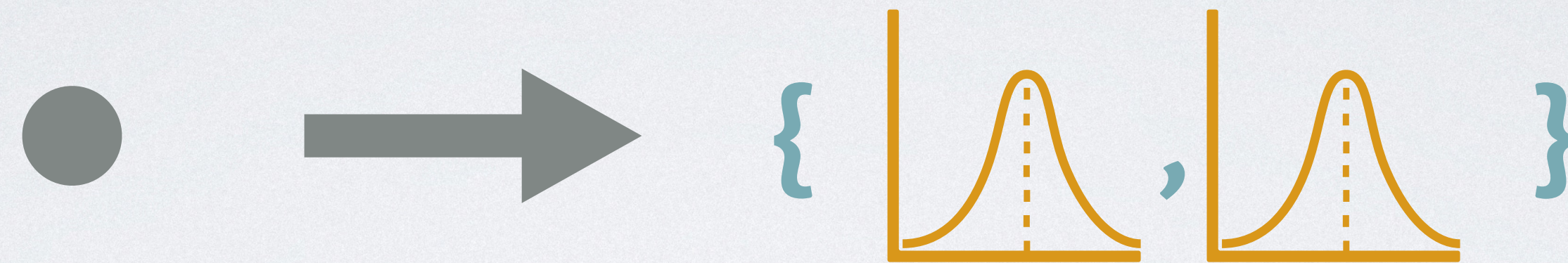




Flexibility: Different Models for Nondeterminism

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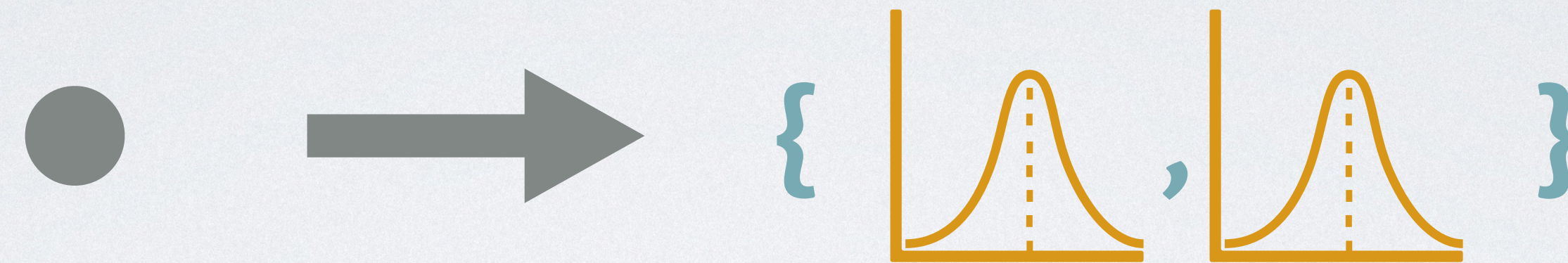
● pGCL:



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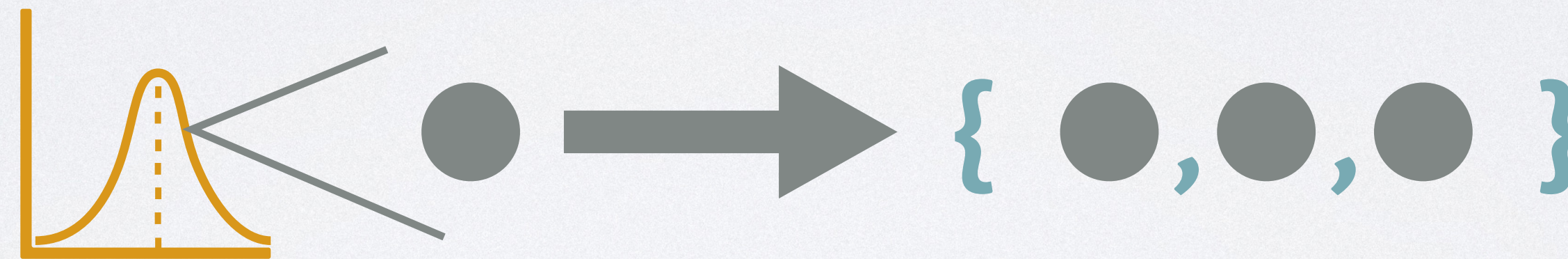
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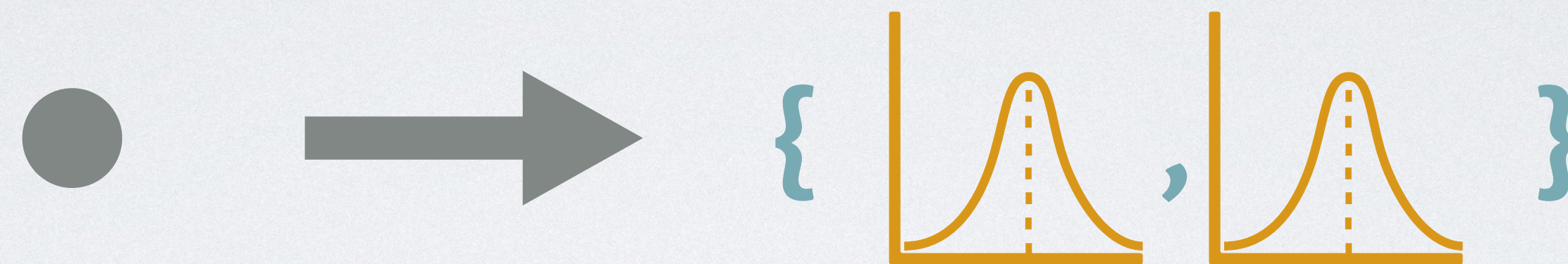
● Cousot's **Probabilistic Abstract Interpretation** (PAI):



$$\mathbb{D}(State \rightarrow \wp(State))$$

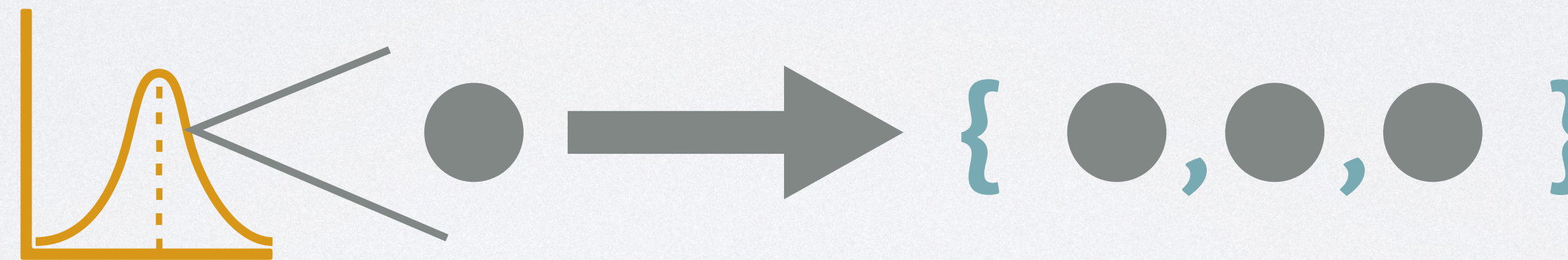
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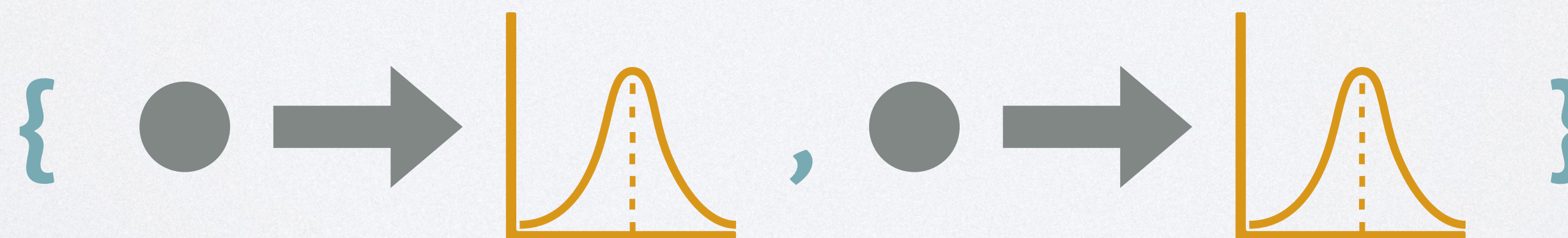
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- **Compile-Time/Relational** Nondeterminism:

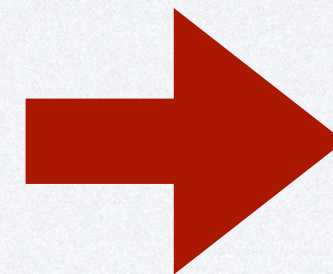


$$\wp(State \rightarrow \mathbb{D}(State))$$

Challenge II:

How to construct recursive program schemes?

```
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od
```


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A Control-flow Graph's Perspective

- **Kleene Algebras** are compatible with **control-flow graphs** via **regular expressions**

Program Construct

A program S
The **control-flow graph** of S

Algebraic Representation

An interpretation $\mathbb{S}$ of S into the algebra
A **regular expression** over $\underline{0}$, $\underline{1}$, $\oplus$, $\otimes$, and $*$

A Control-flow Graph's Perspective

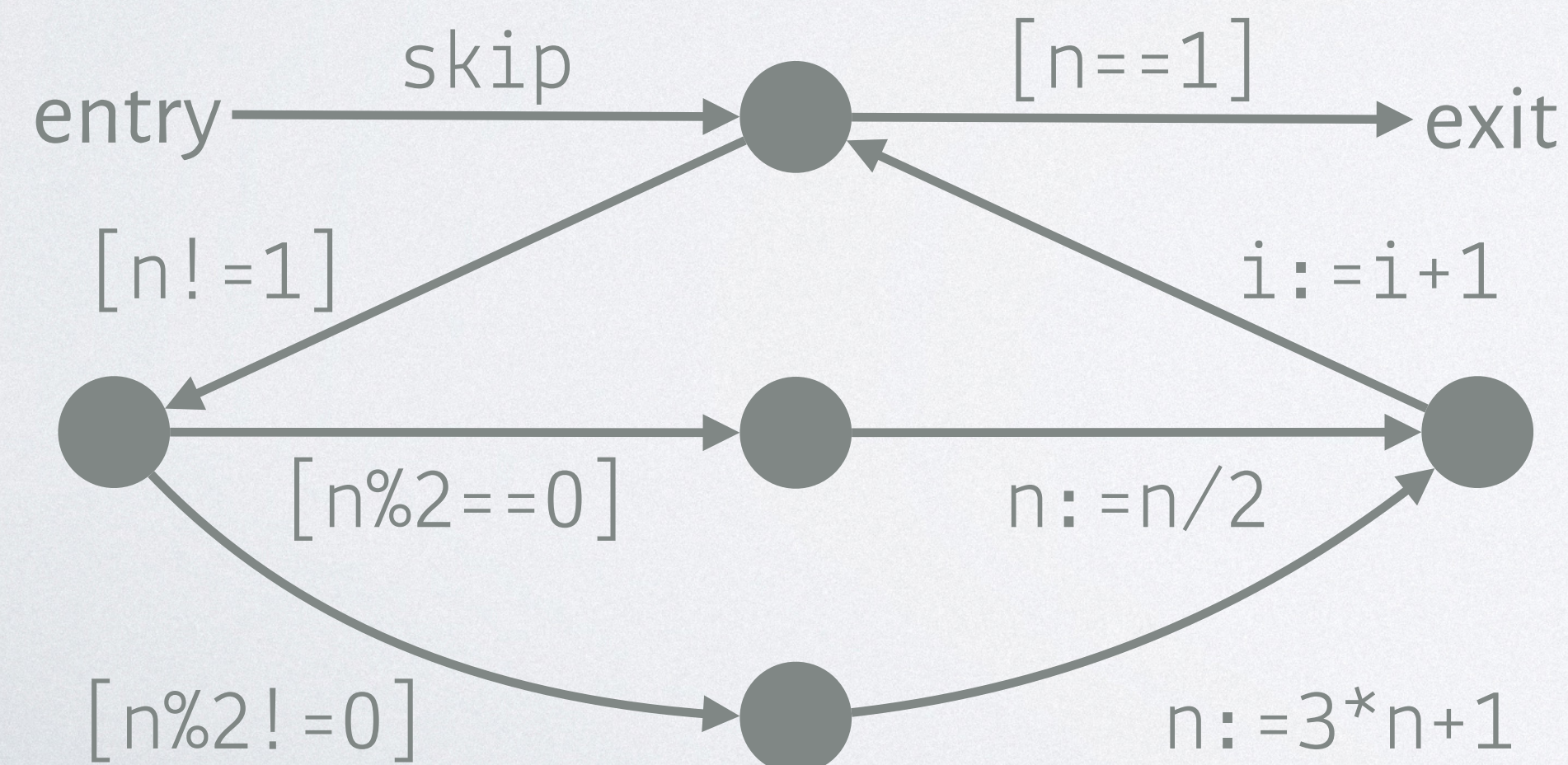
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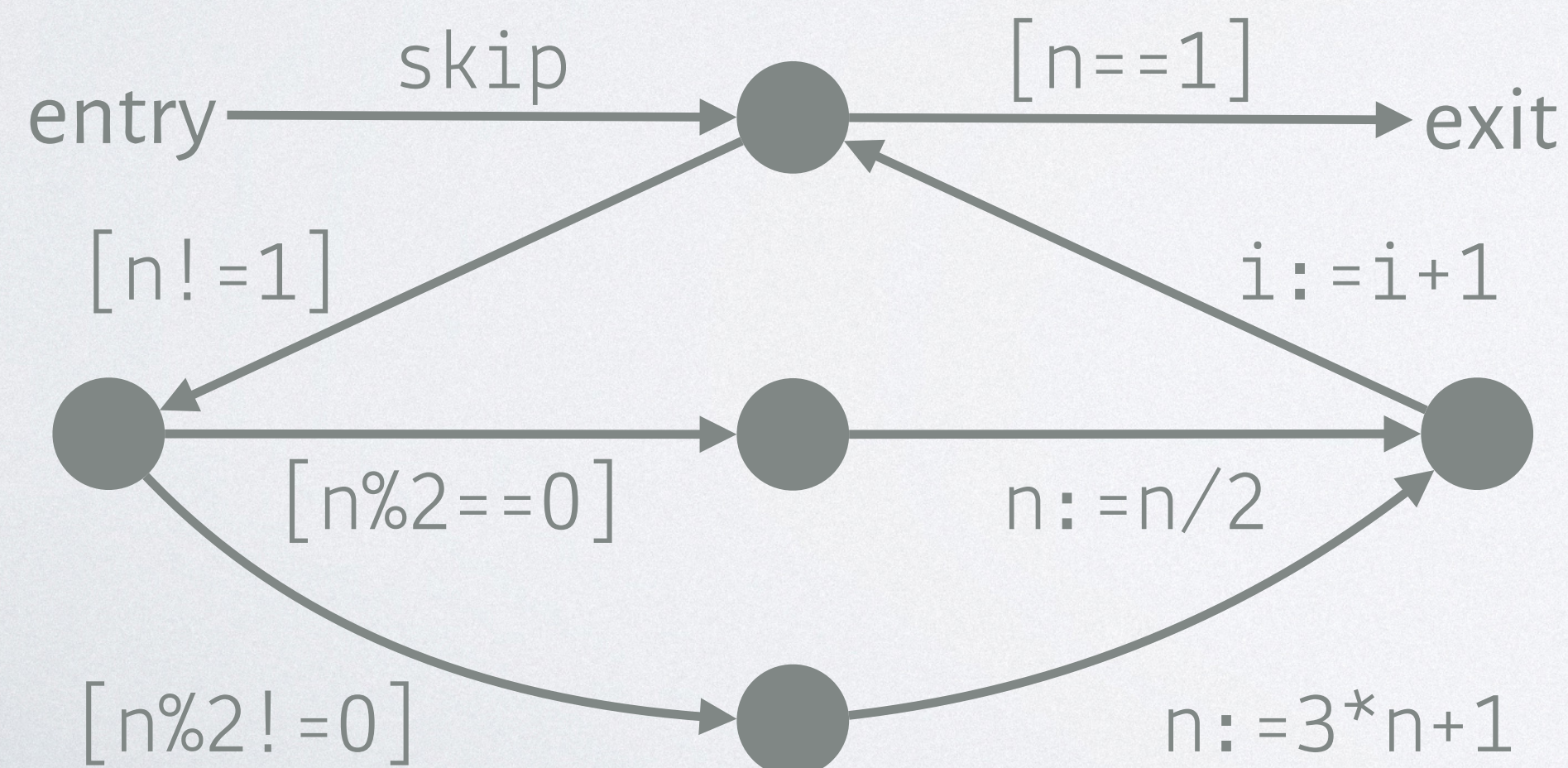
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$$\left([n!=1] \otimes \left(\begin{array}{c} [n\%2==0] \otimes n:=n/2 \\ [n\%2!=0] \otimes n:=3*n+1 \end{array} \oplus \right) \otimes i:=i+1 \right)^* \otimes [n==1]$$



Do Control-flow Graphs Suffice?

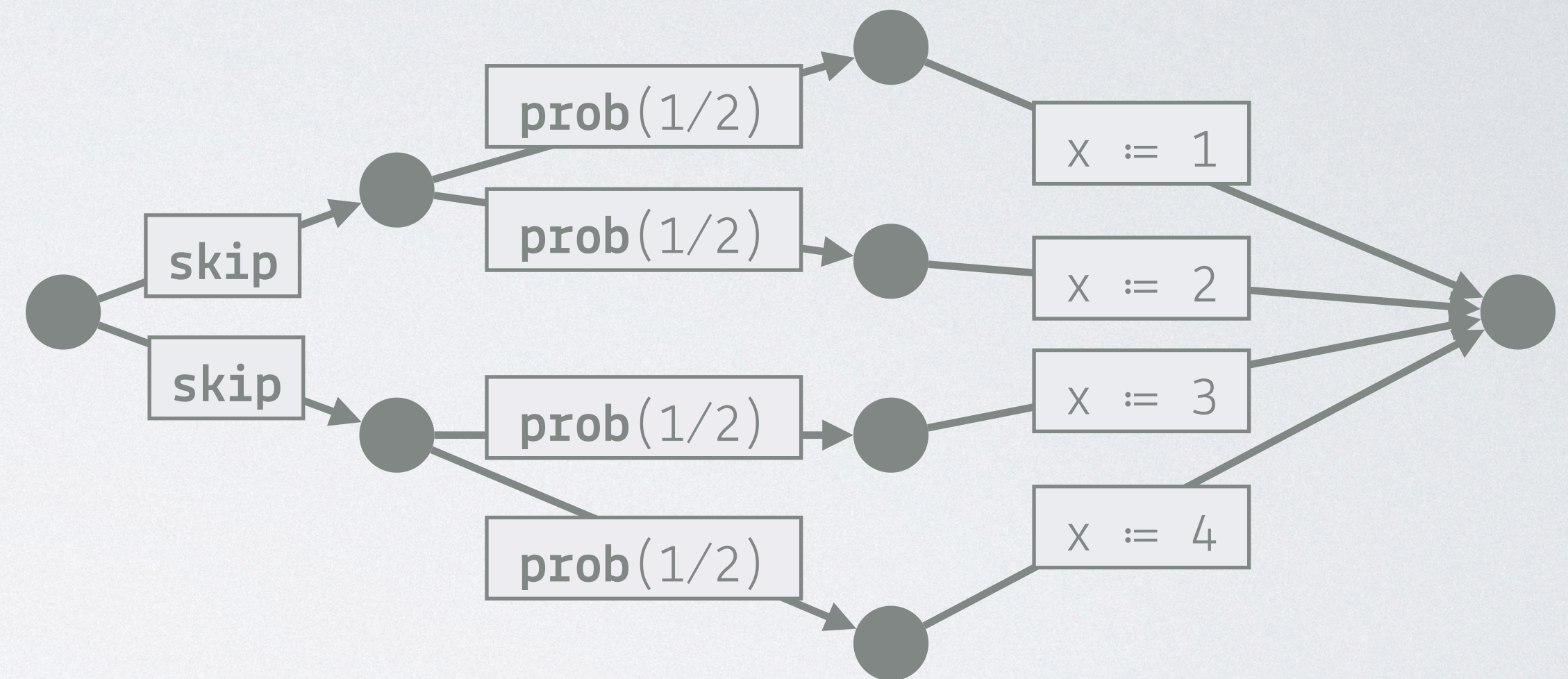
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```
if
| true → x : $\in_p$  (1 @ 1/2 | 2 @ 1/2)
| true → x : $\in_p$  (3 @ 1/2 | 4 @ 1/2)
fi
```

Do Control-flow Graphs Suffice?

```

if
| true →  $x \in_p (1 @ 1/2 \mid 2 @ 1/2)$ 
| true →  $x \in_p (3 @ 1/2 \mid 4 @ 1/2)$ 
fi
  
```

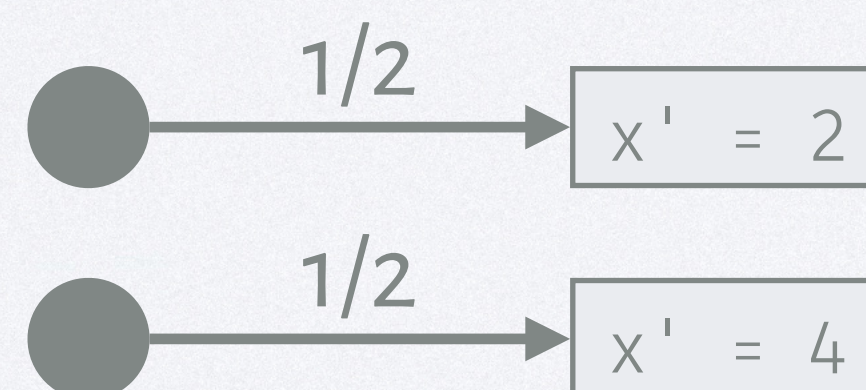
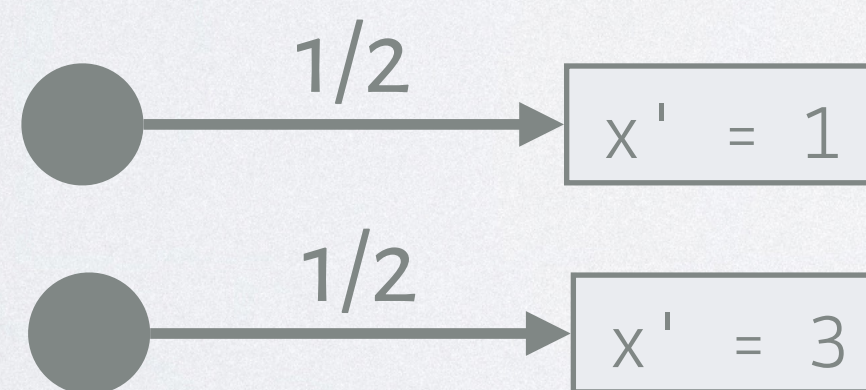
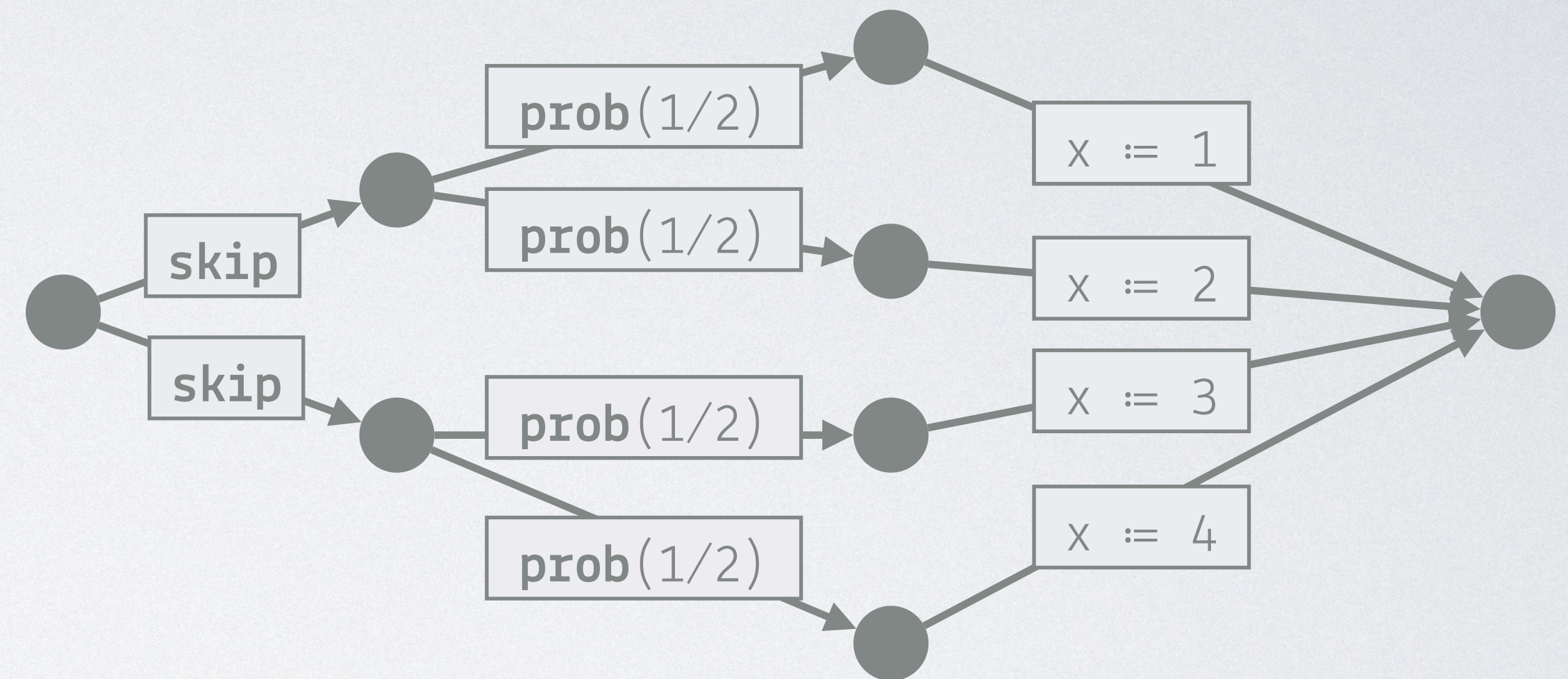


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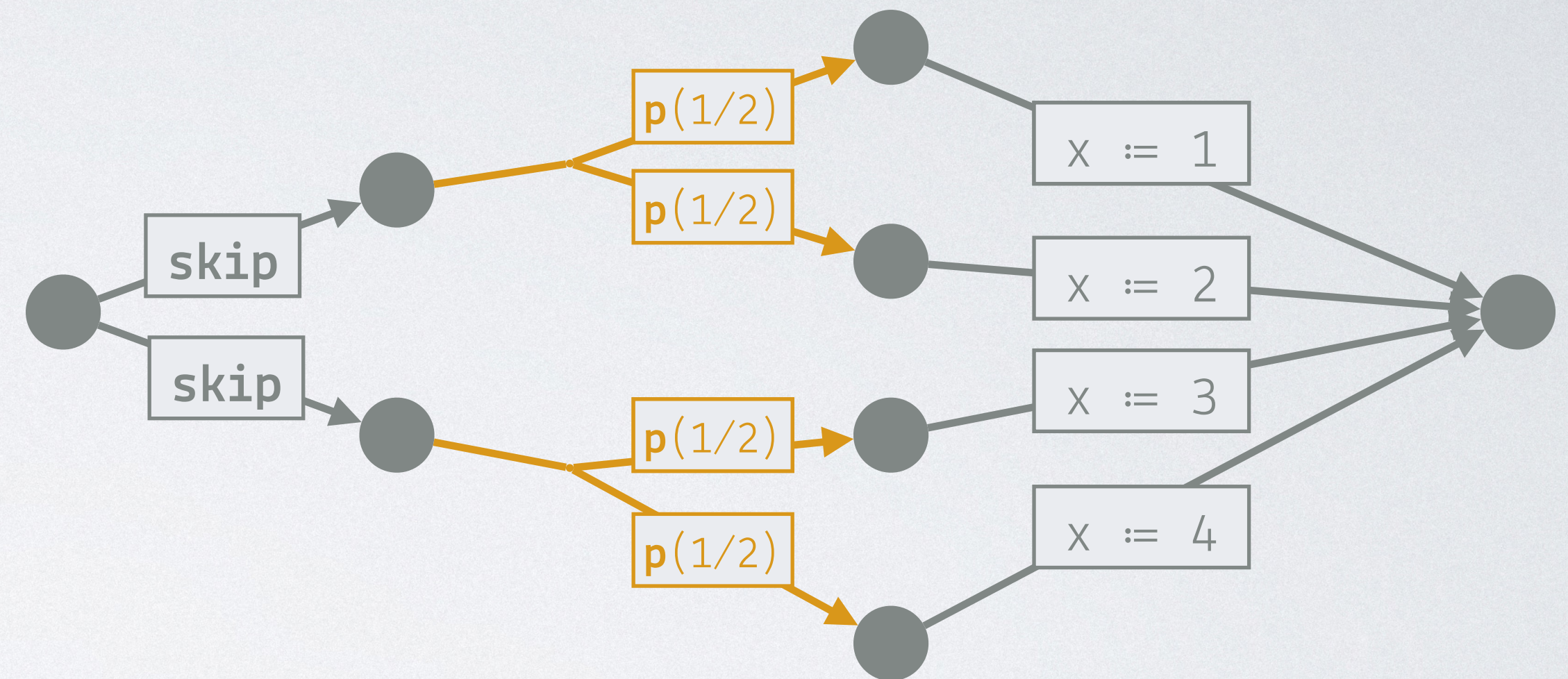
Probabilities sum up to 2!

Our Approach: Control-flow Hyper-graphs

```

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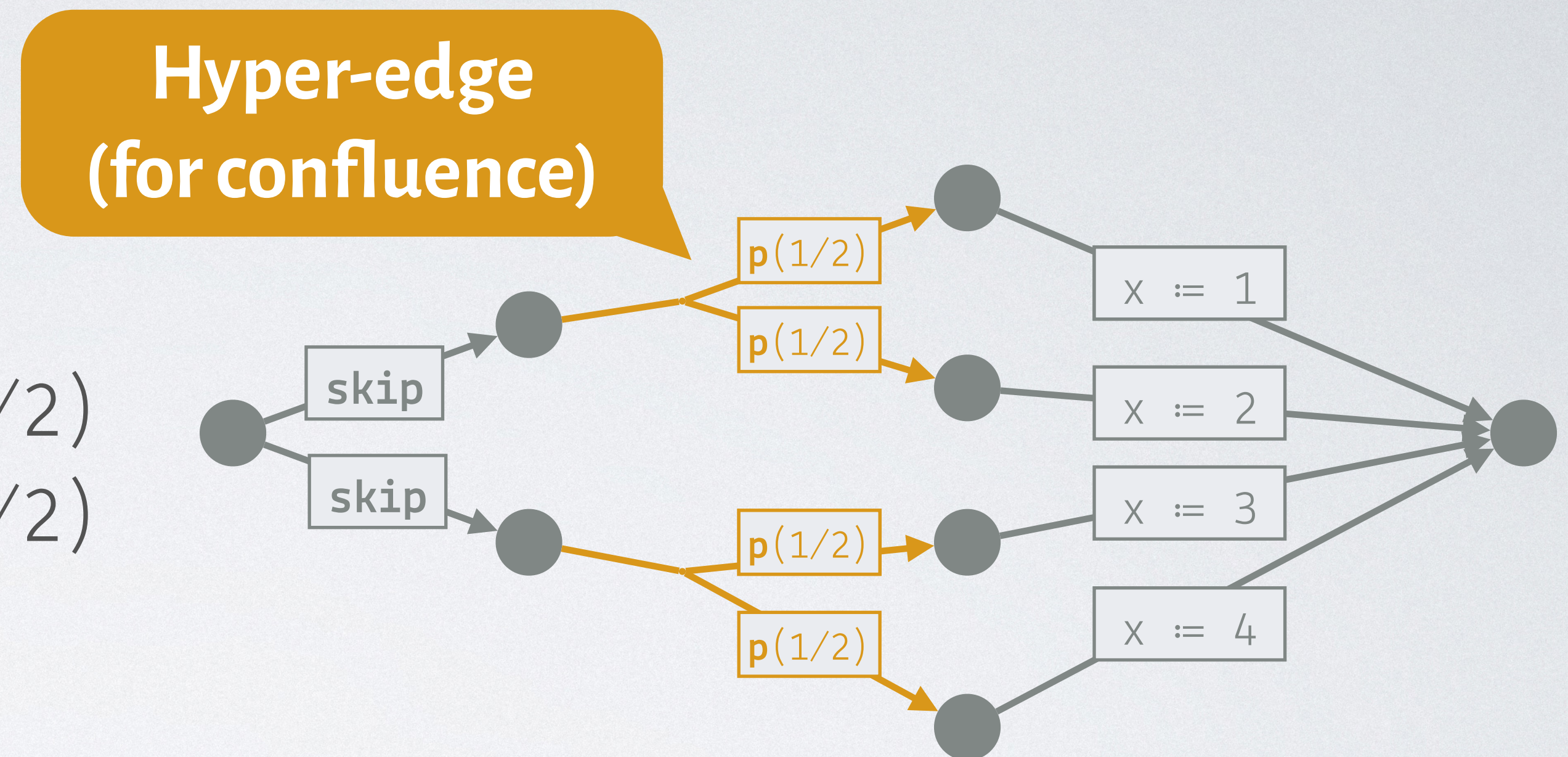
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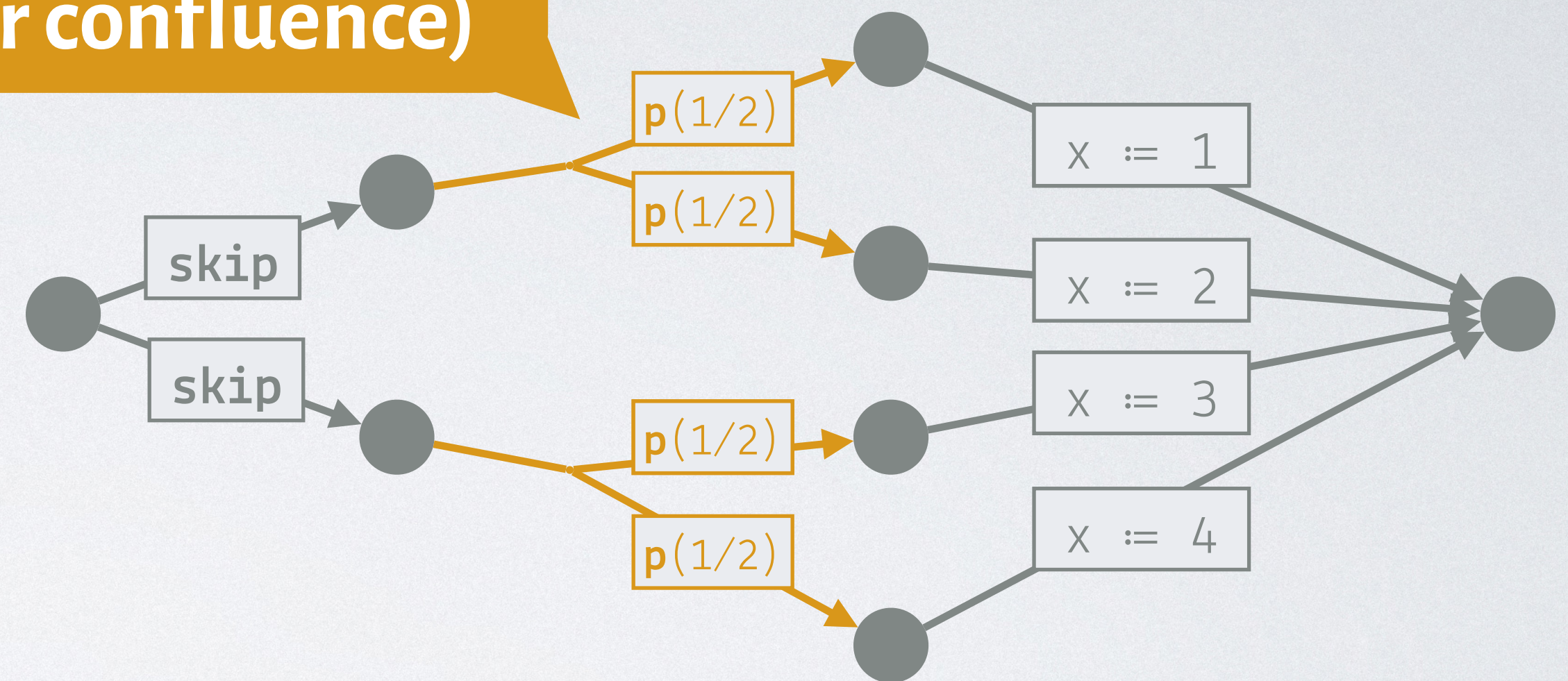
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fi

```

**Hyper-edge
(for confluence)**

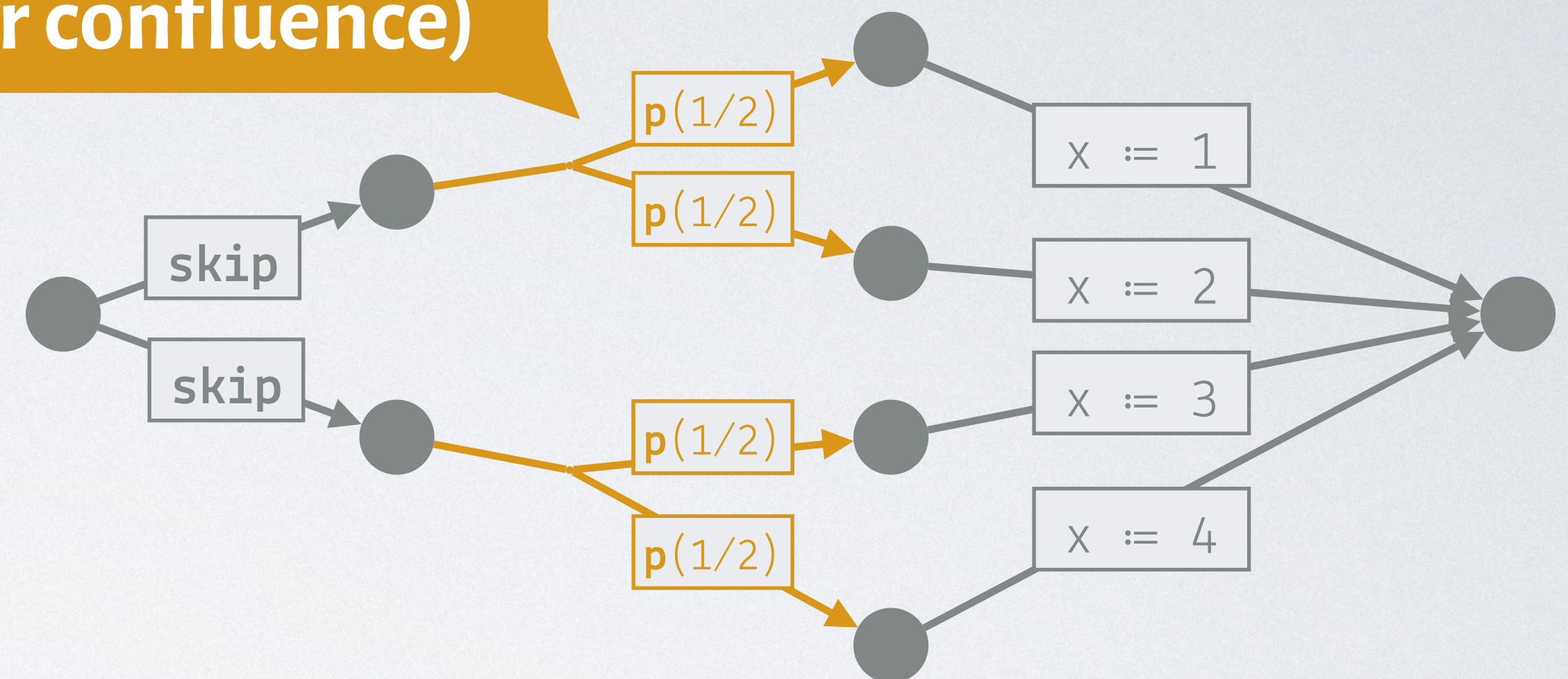


Our Approach: Control-flow Hyper-graphs

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**Hyper-edge
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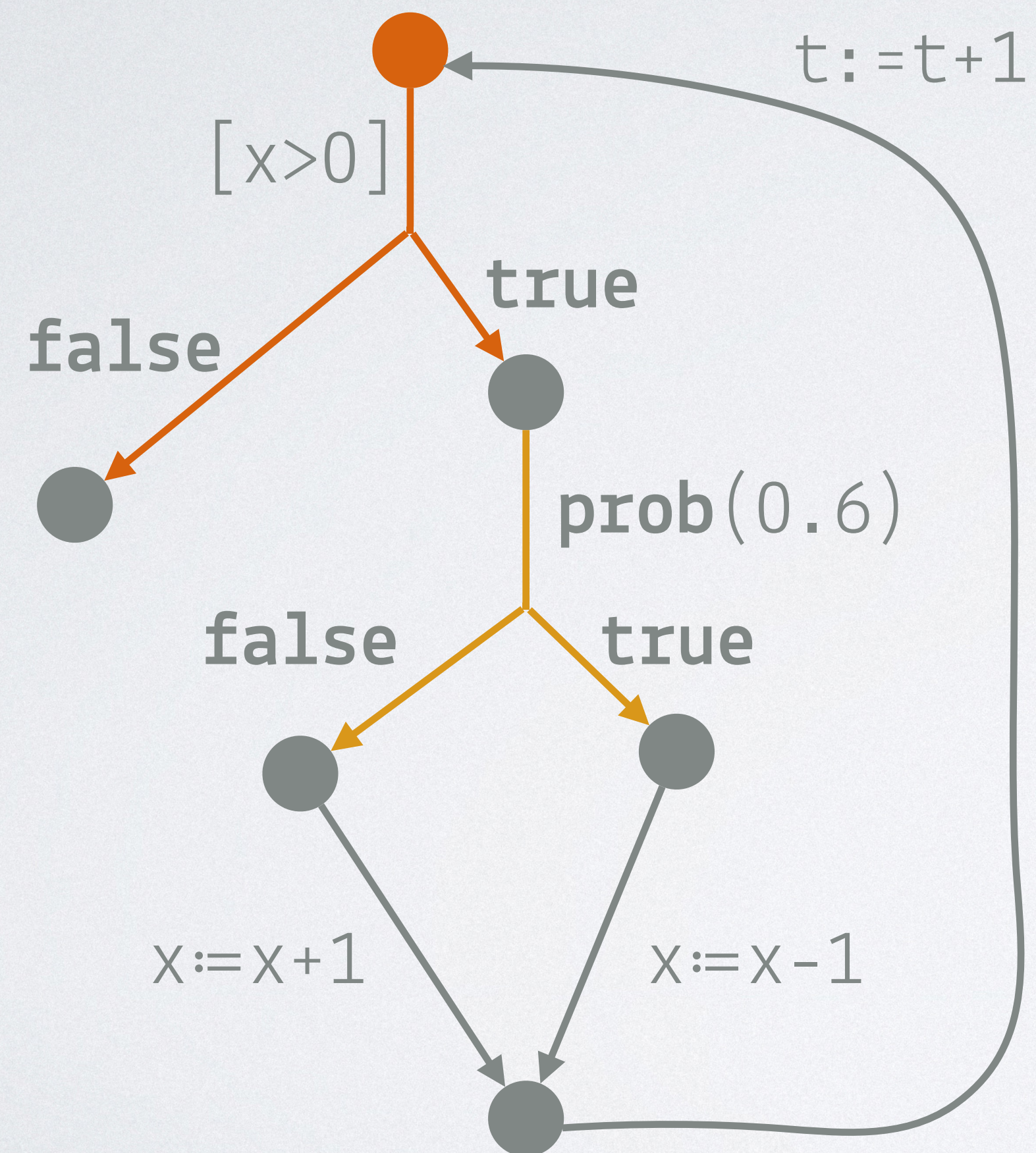
**Hyper-path
(like a tree)**



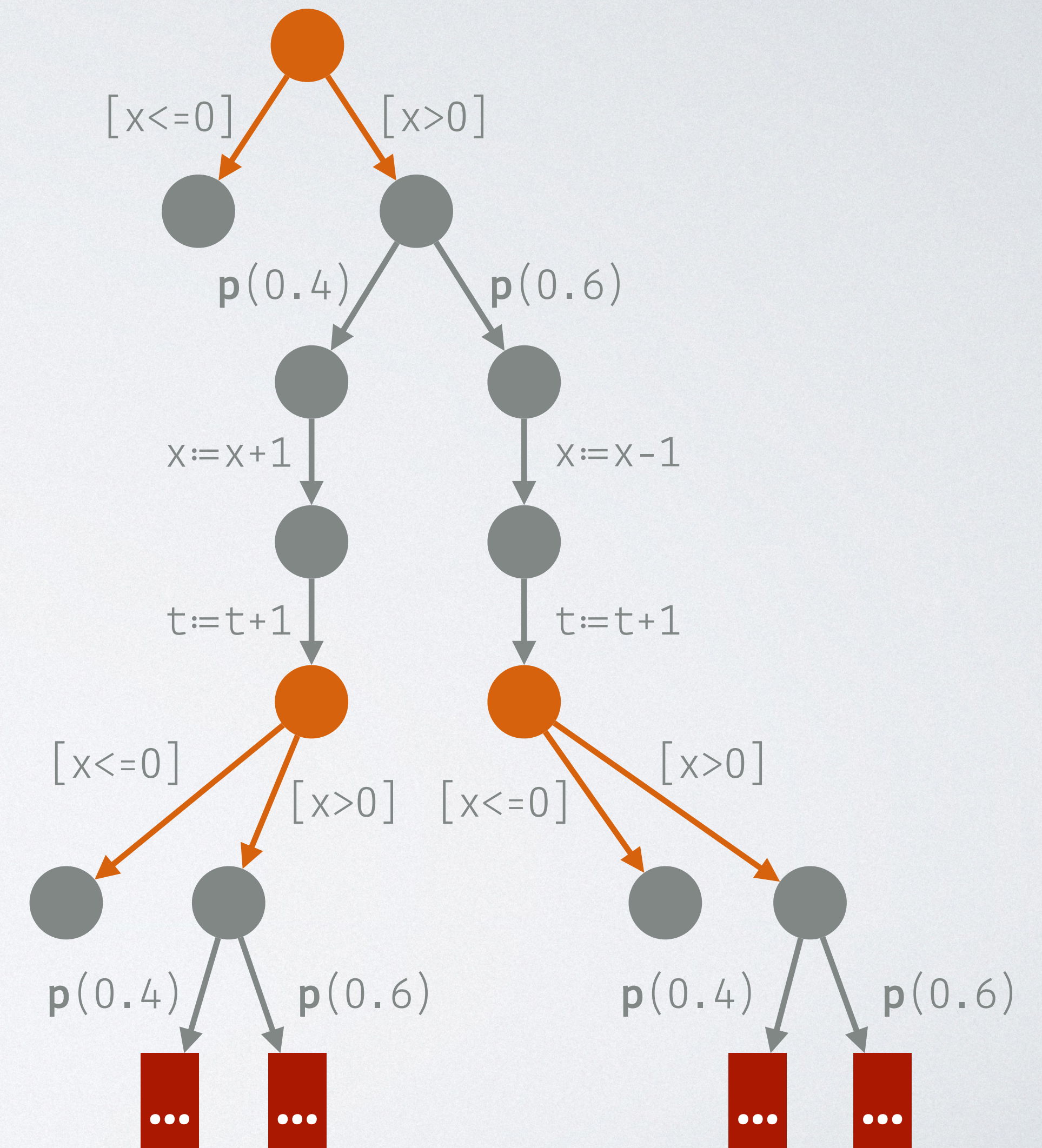
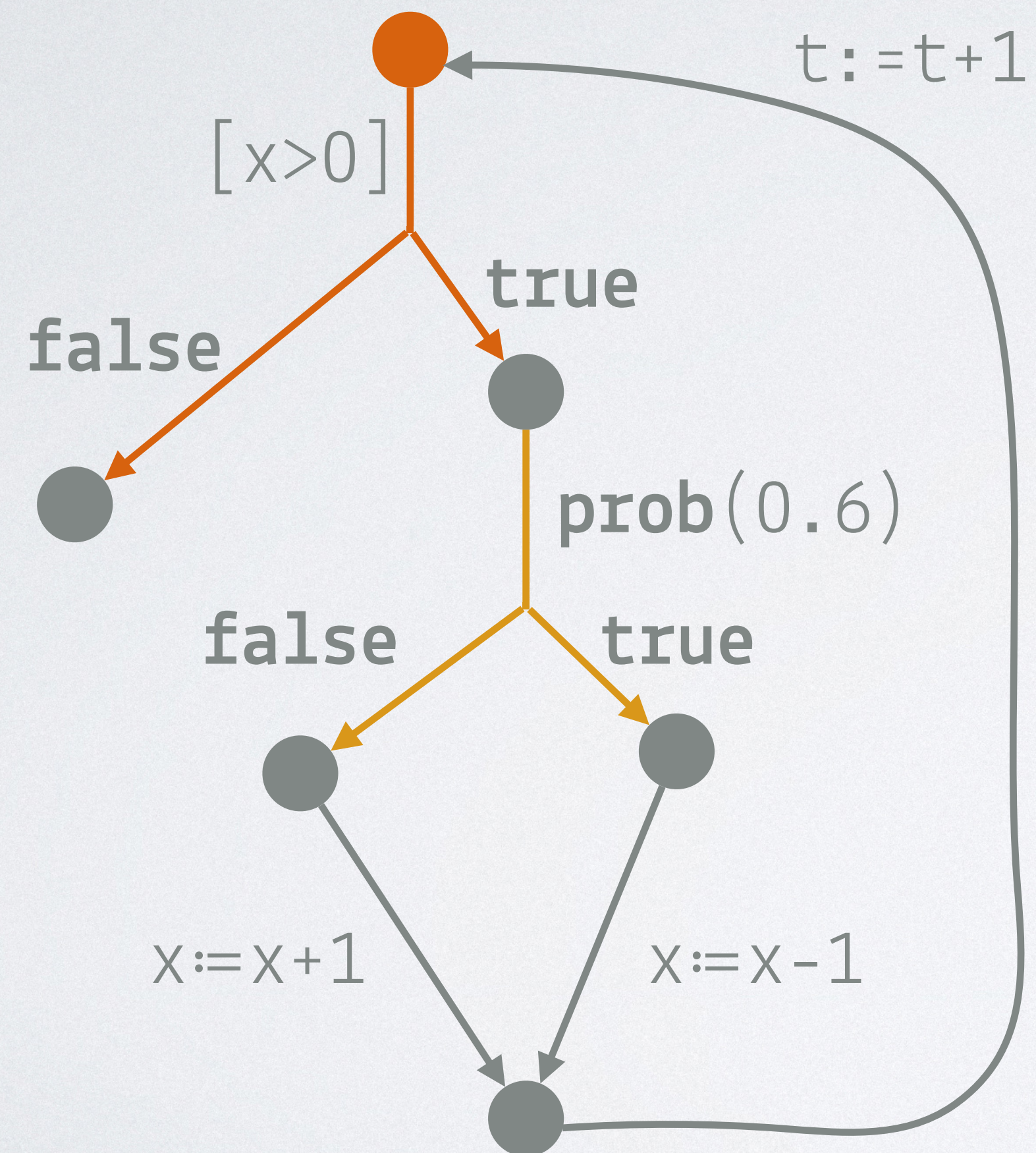


Hyper-paths are Infinite Trees!

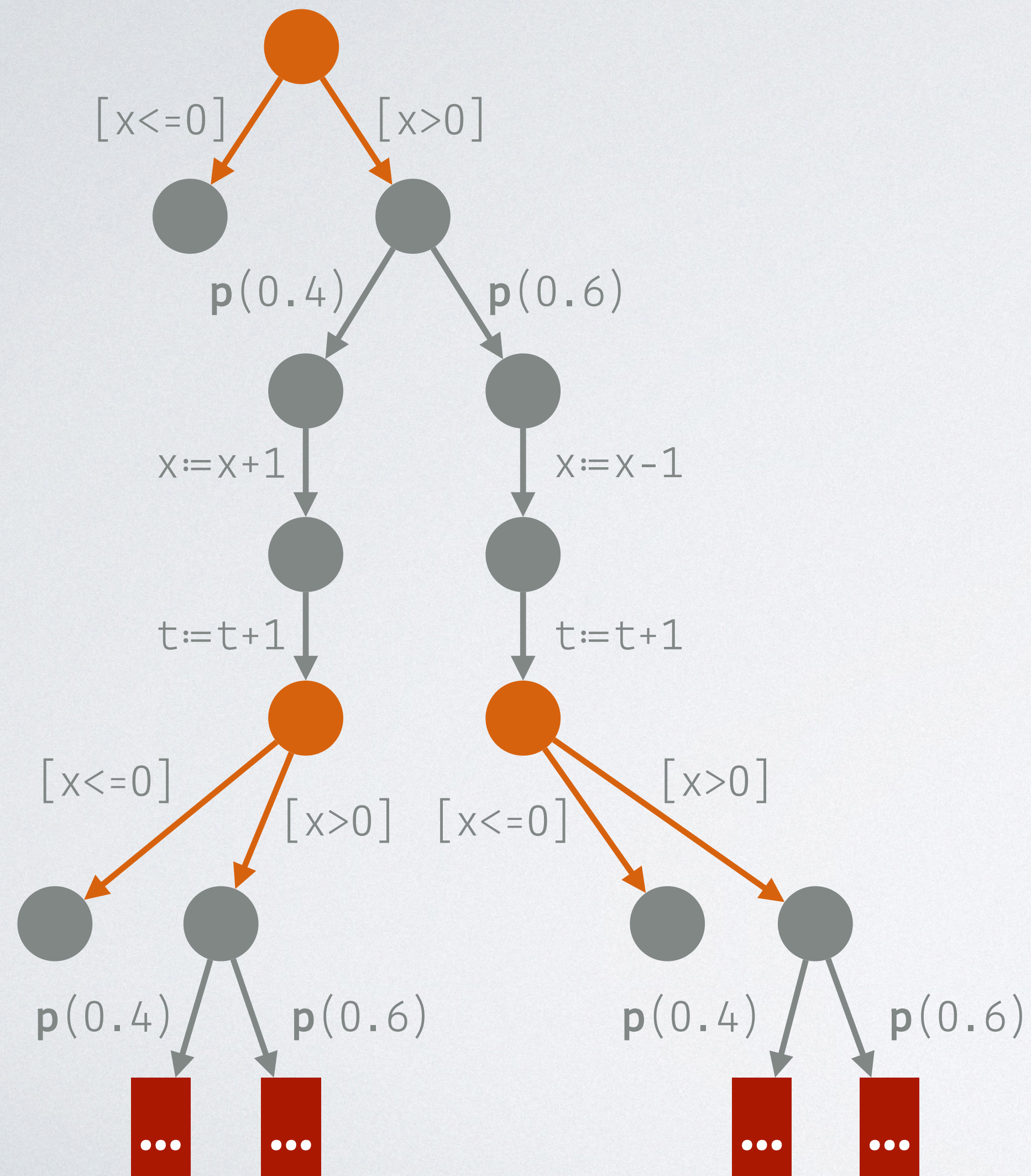
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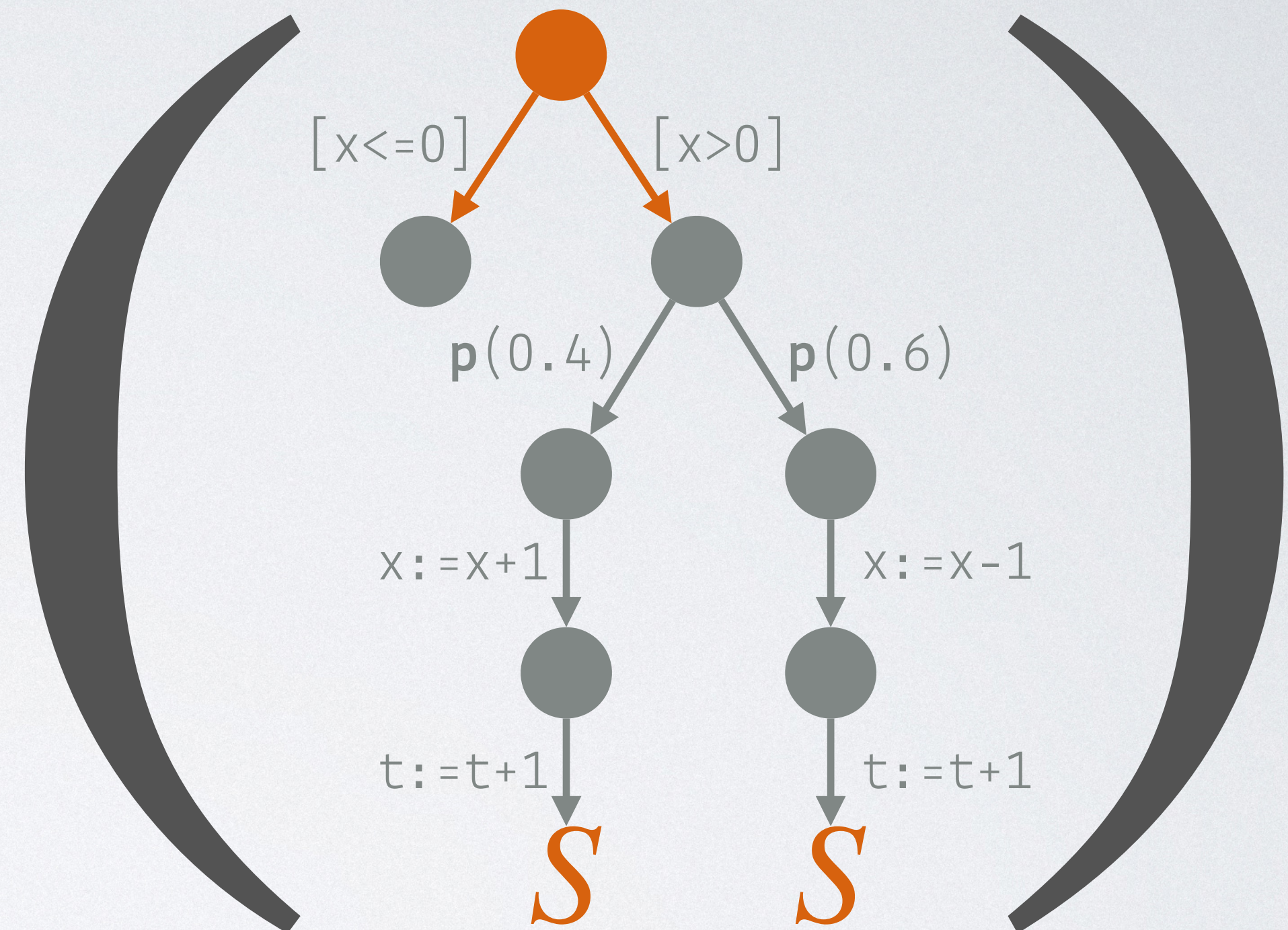
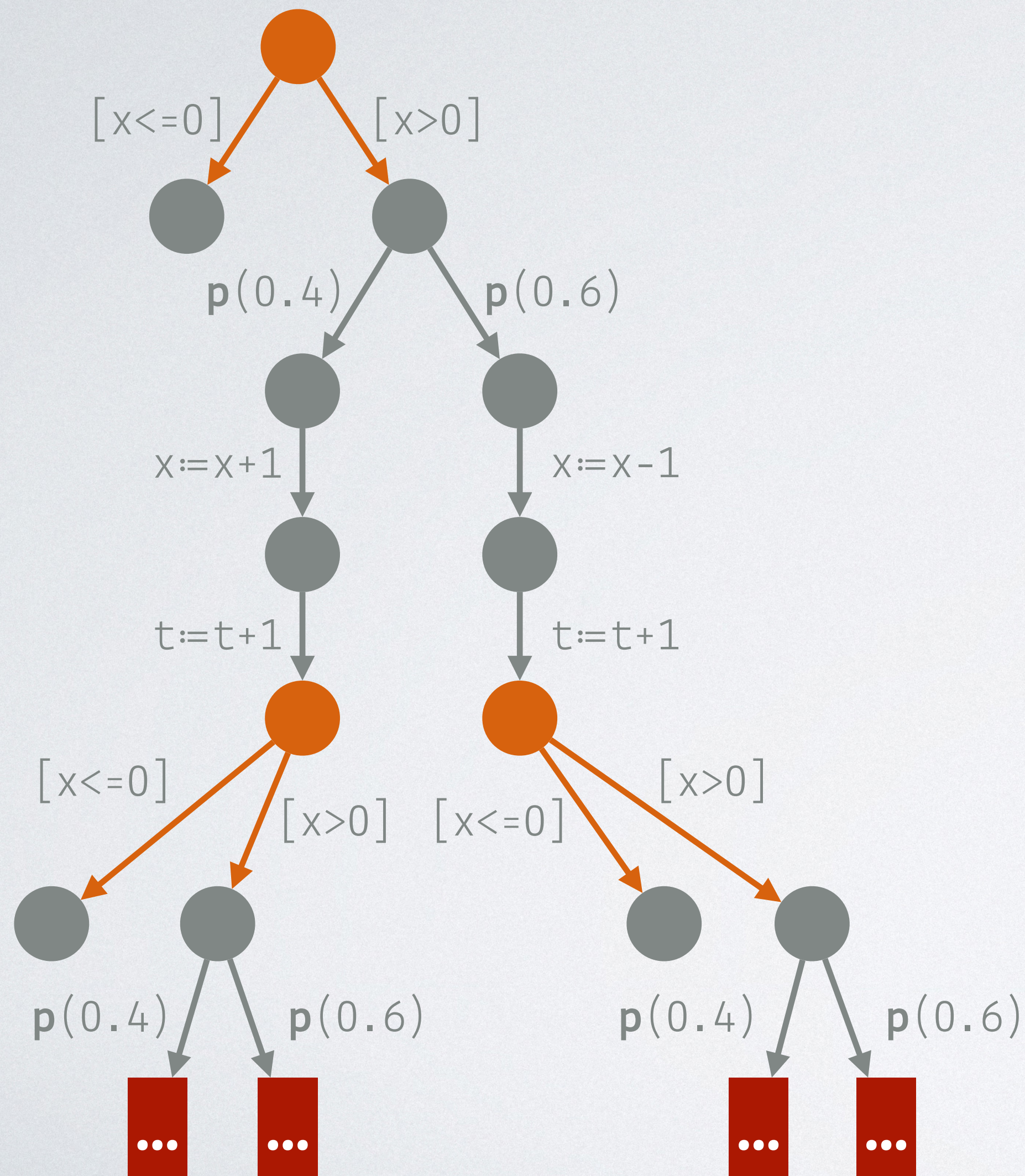
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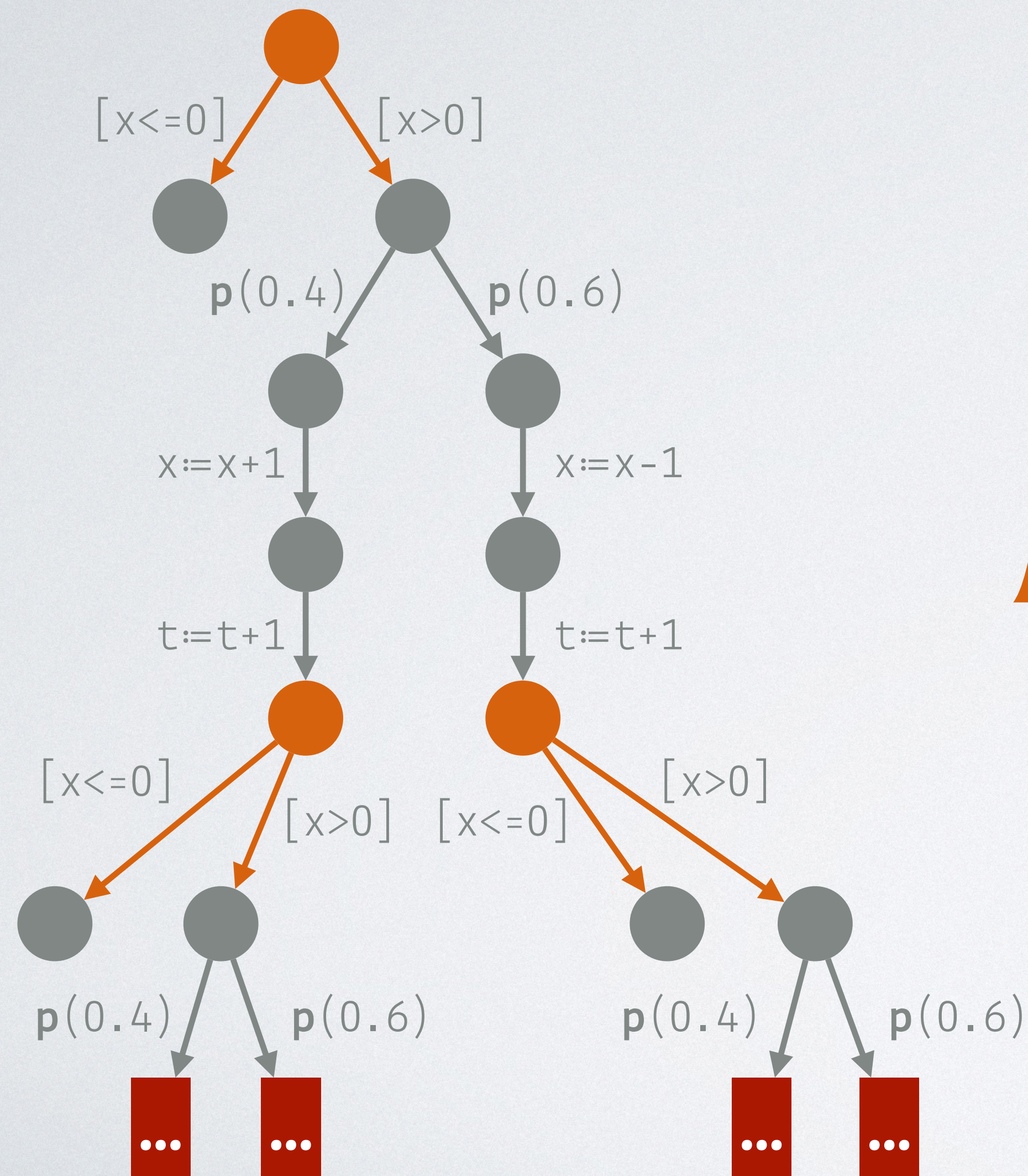
Recursive Program Schemes



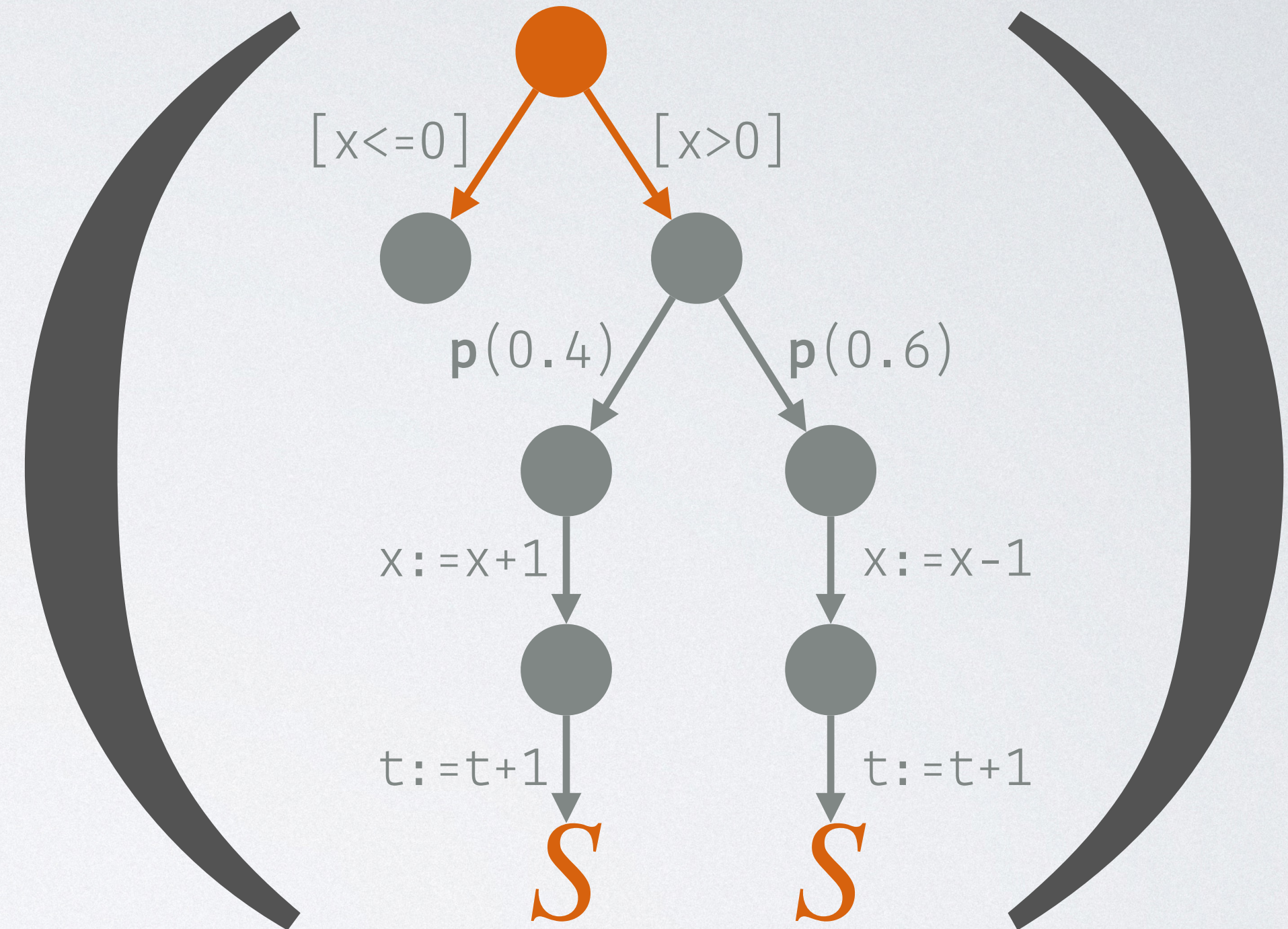
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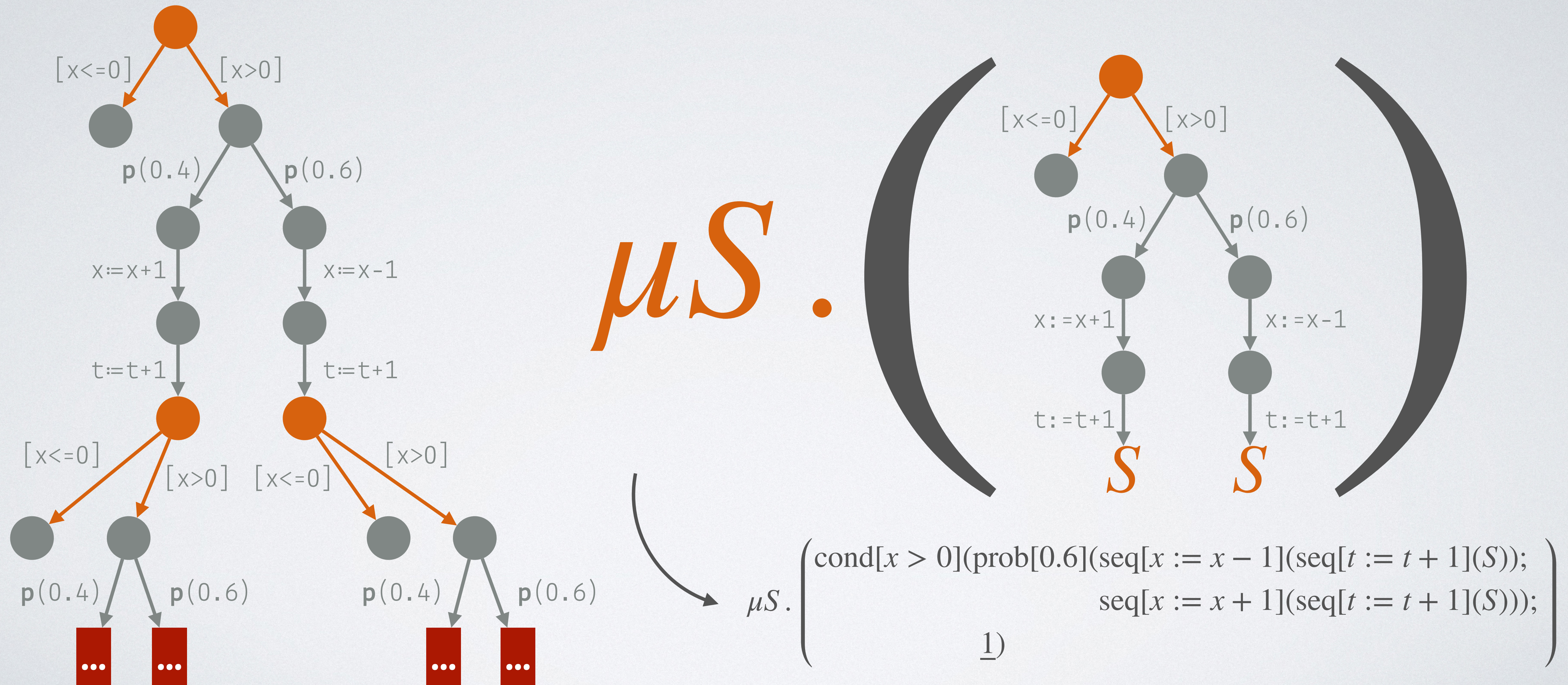
Recursive Program Schemes



μS



Recursive Program Schemes





A Control-flow Hyper-graph's Perspective

- © **Markov Algebras** are compatible with **control-flow hyper-graphs** via **recursive program schemes**

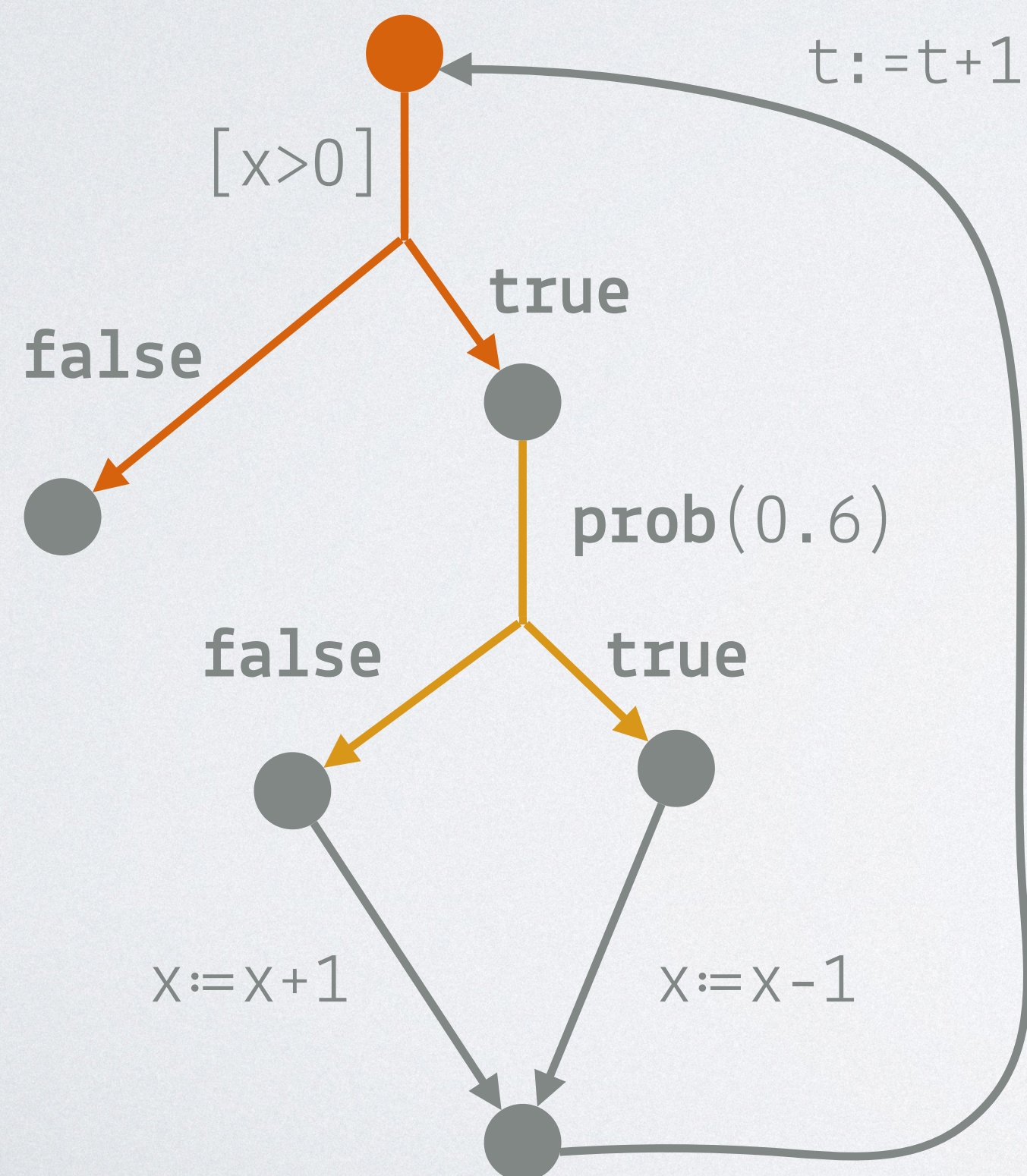
A Control-flow Hyper-graph's Perspective

- **Markov Algebras** are compatible with **control-flow hyper-graphs** via **recursive program schemes**

```
while  $x > 0$  do
  if prob(0.6) then  $x := x + 1$ 
  else  $x := x - 1$  fi;
   $t := t + 1$ 
od
```

A Control-flow Hyper-graph's Perspective

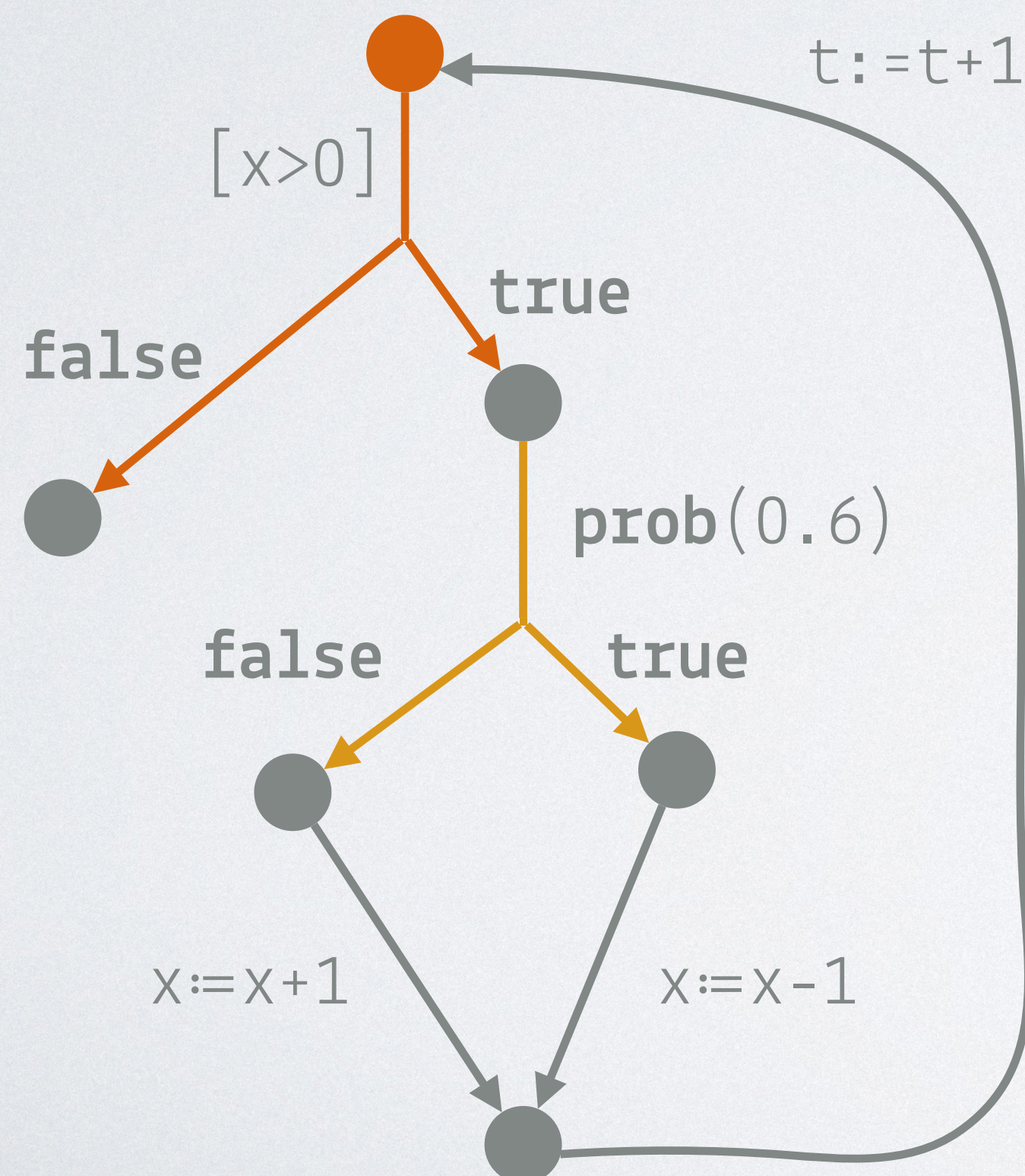
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A Control-flow Hyper-graph's Perspective

- **Markov Algebras** are compatible with **control-flow hyper-graphs** via **recursive program schemes**



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while  $x > 0$  do
  if prob(0.6) then  $x := x + 1$ 
  else  $x := x - 1$  fi;
   $t := t + 1$ 
od

```

$$\mu S. \left(\begin{array}{l} \text{cond}[x > 0](\text{prob}[0.6](\text{seq}[x := x - 1](\text{seq}[t := t + 1](S)); \\ \text{seq}[x := x + 1](\text{seq}[t := t + 1](S))))); \\ \underline{1} \end{array} \right)$$

Challenge III:

How to carry out quantitative analyses efficiently?

```
while prob(2/3) do  
  x := x + 1  
od
```

Iterative Analysis

```
while prob(2/3) do  
  x := x + 1  
od
```

$$\mu S . ((x := x+1) \otimes S)_{2/3} \oplus \text{skip}$$

Iterative Analysis

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while prob(2/3) do  
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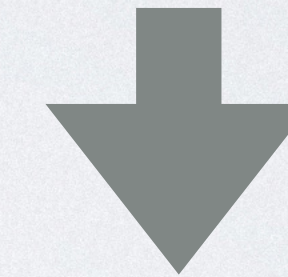
$$\mu S . ((x := x+1) \otimes S)_{2/3} \oplus \text{skip}$$

- Markov algebra for computing $\mathbb{E}[\Delta x]$
 - Sequencing: $r \otimes t \triangleq r + t$
 - Branching: $r_p \oplus t \triangleq p * r + (1 - p) * t$

Iterative Analysis

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while prob(2/3) do
  x := x + 1
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$$\kappa^{(0)} = 0$$

$$\kappa^{(1)} = 2/3 * (1 + \kappa^{(0)}) + 1/3 * 0 = 2/3$$

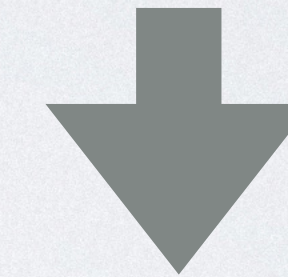
$$\kappa^{(2)} = 2/3 * (1 + \kappa^{(1)}) + 1/3 * 0 = 10/9$$

...

$$\kappa^{(\infty)} = 2$$

Iterative Analysis

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while prob(2/3) do
  x := x + 1
od
```

$$\mu S . ((x := x+1) \otimes S)_{2/3} \oplus \text{skip}$$


- Markov algebra for computing $\mathbb{E}[\Delta x]$
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$$\kappa^{(2)} = 2/3 * (1 + \kappa^{(1)}) + 1/3 * 0 = 10/9$$

...

$$\kappa^{(\infty)} = 2$$

Need ∞ iterations to converge!

Non-iterative Analysis

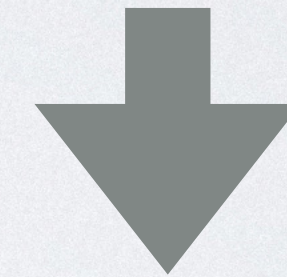
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Non-iterative Analysis

```
while prob(2/3) do
  x := x + 1
od
```

$$\mu S . ((x := x+1) \otimes S)_{2/3} \oplus \text{skip}$$


Equivalent to solve:

$$s = 2/3 * (1 + s) + 1/3 * 0,$$

Analytical solution:

$$s = 2$$

No need for iteration!

- Markov algebra for computing $\mathbb{E}[\Delta x]$
- Sequencing: $r \otimes t \triangleq r + t$
- Branching: $r_p \oplus t \triangleq p * r + (1 - p) * t$



Non-iterative **Intra**-procedural Analysis

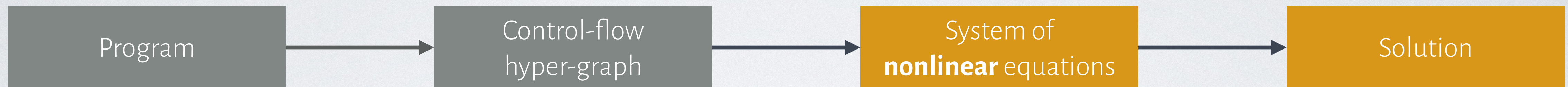
Non-iterative **Intra**-procedural Analysis

- Observation: Loops are (right-) **linear recursions**, thus we can always extract a system of **linear equations**
 - For each $\mu S . E$, we extract an equation $S = E$

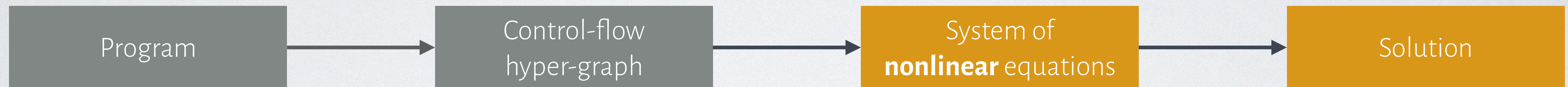
Non-iterative **Intra**-procedural Analysis

- Observation: Loops are (right-) **linear recursions**, thus we can always extract a system of **linear equations**
 - For each $\mu S . E$, we extract an equation $S = E$
- Techniques to solve linear equation systems extracted from probabilistic programs:
 - **Linear Programming:** Compute probabilities or expectations
 - **Loop-Invariant Generation:** Derive probabilistic or expectation invariants

Inter-procedural Analysis

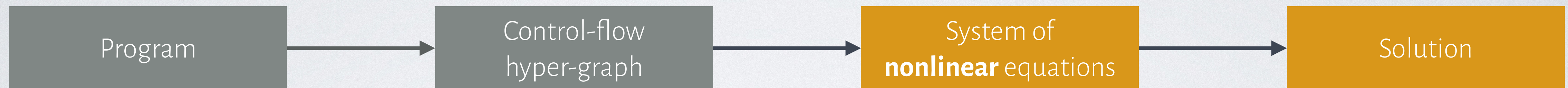


Inter-procedural Analysis

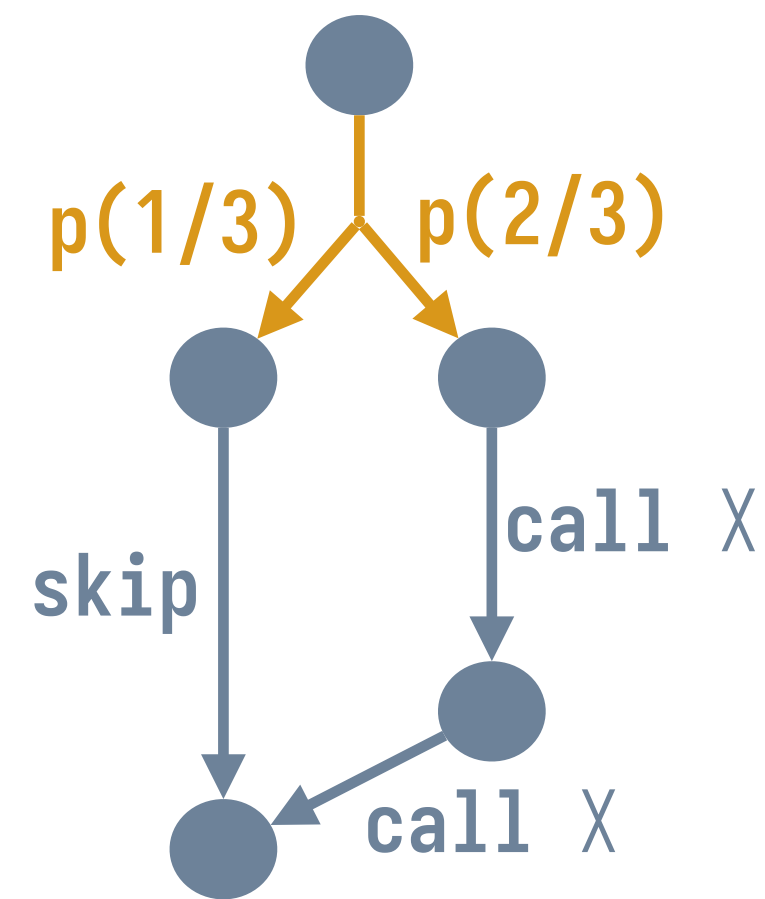


```
proc X begin
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  then skip
  else
    call X;
    call X
  fi
end
```

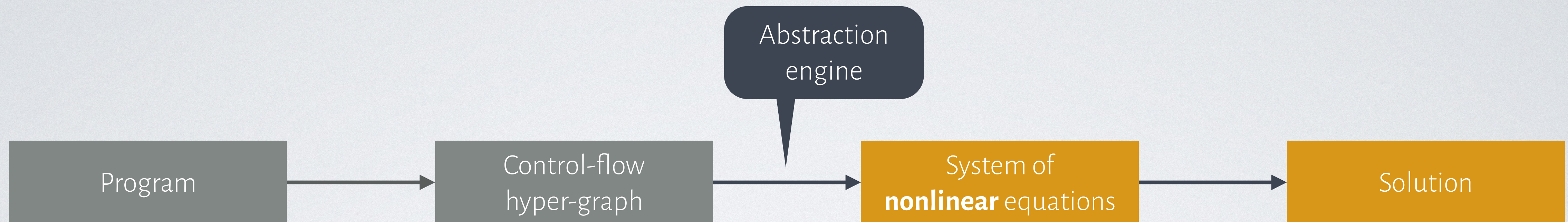
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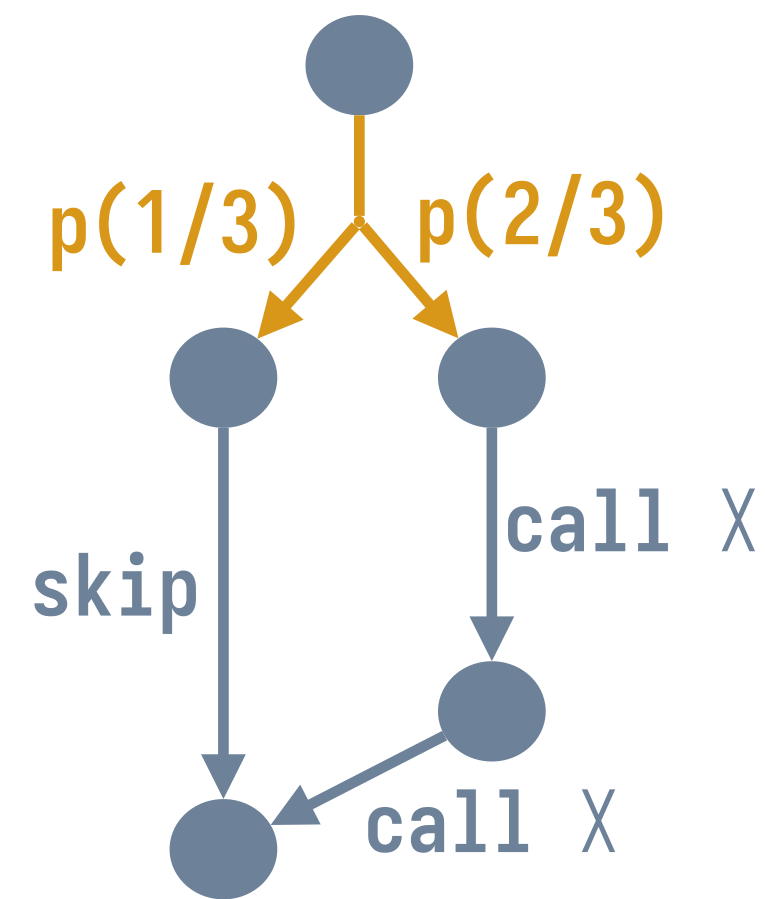
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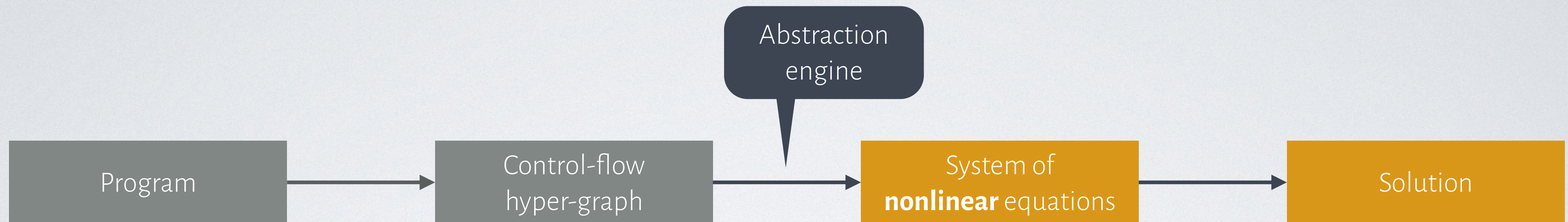
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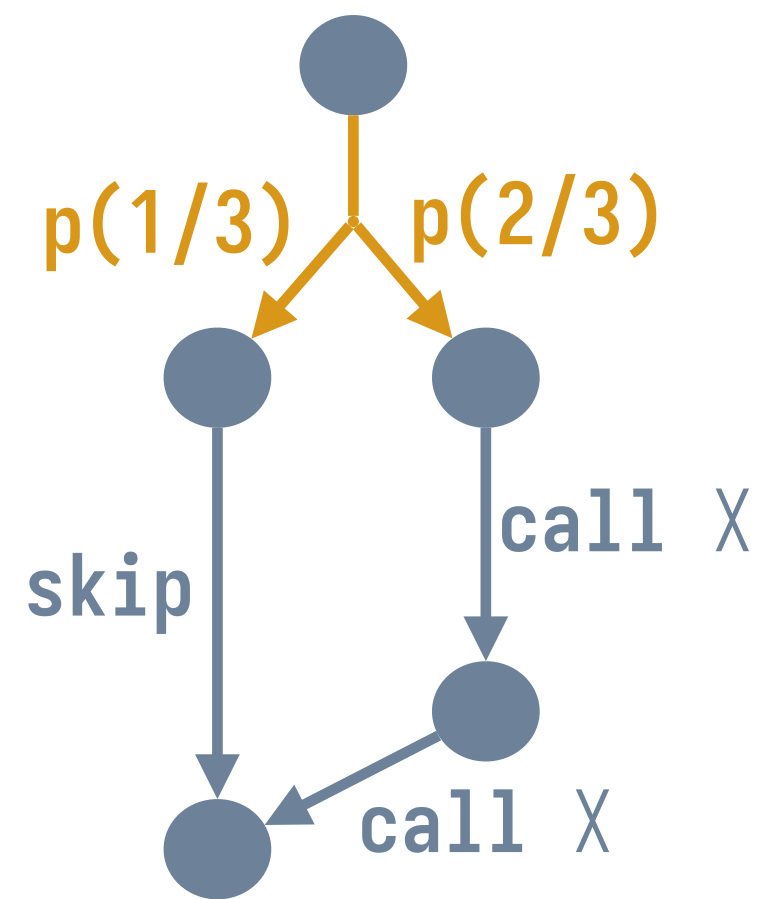


Inter-procedural Analysis



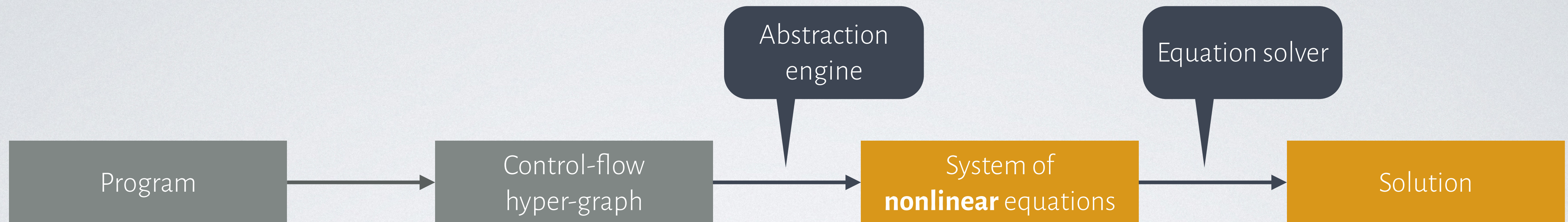
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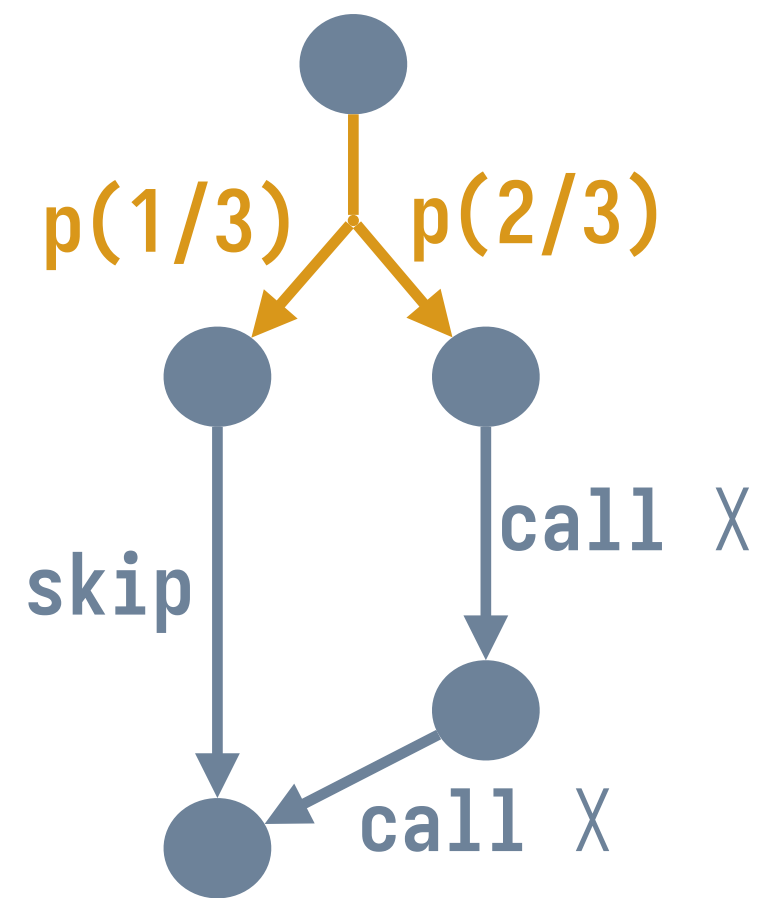
$$X = (\text{skip} \otimes \underline{1})_{1/3} \oplus (X \otimes X \otimes \underline{1})$$

Inter-procedural Analysis



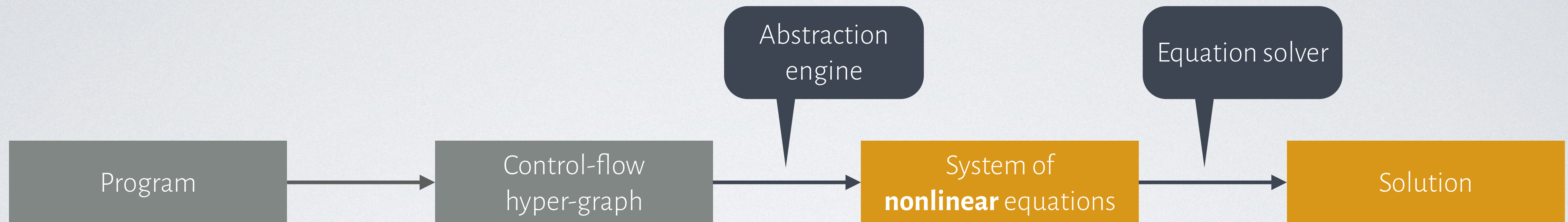
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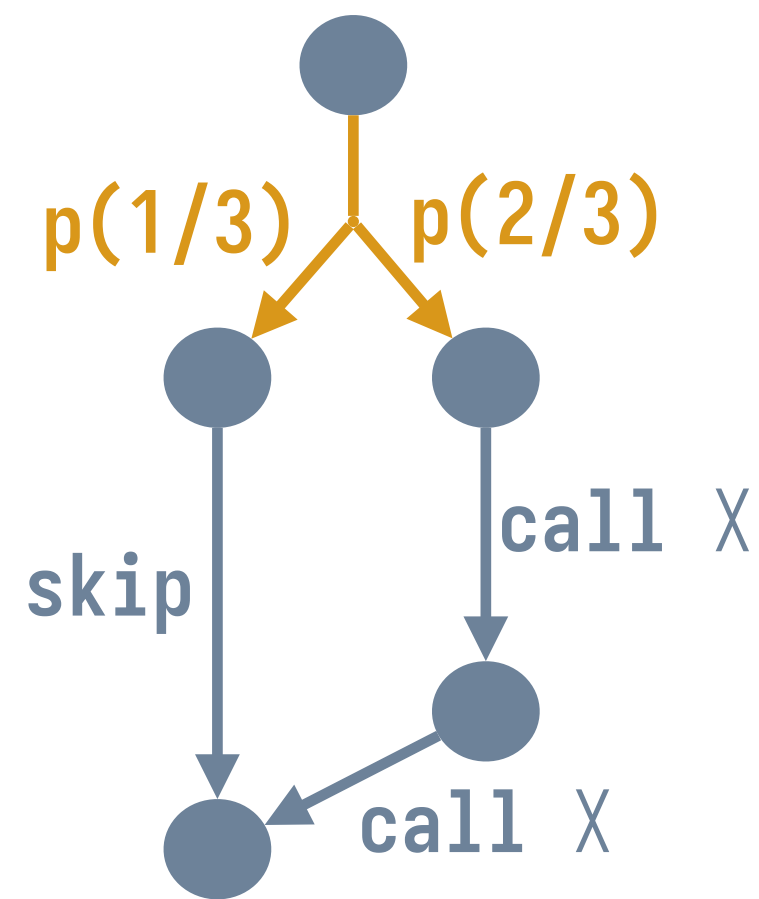
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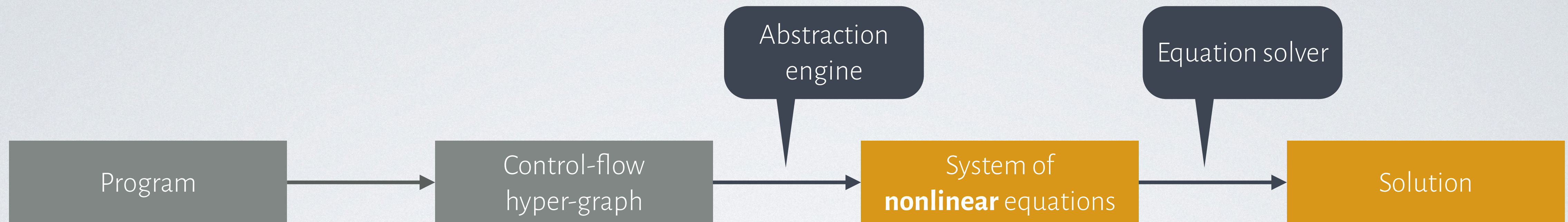
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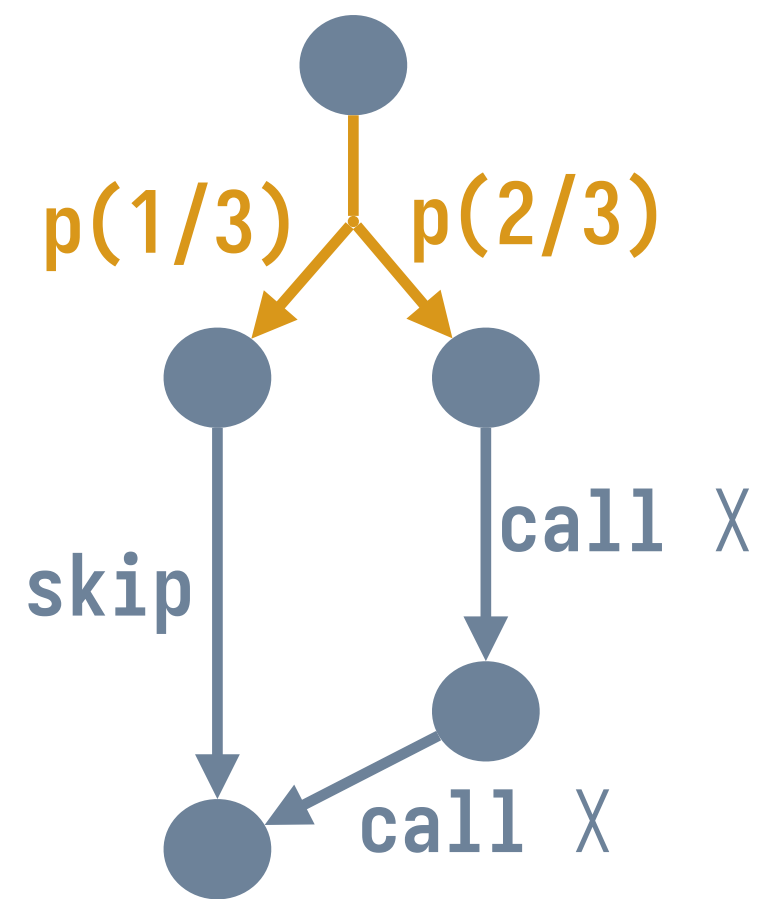
X = "termination probability is 1/2"

Inter-procedural Analysis



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$$X = (\text{skip} \otimes \underline{1})_{1/3} \oplus (X \otimes X \otimes \underline{1})$$

X = "termination probability is 1/2"

Also a **procedure summary** for X



The **Functional** Approach for Inter-procedural Analysis

The **Functional** Approach for Inter-procedural Analysis

- Let X_i represent the **procedure summary** of P_i

$$\begin{aligned} X_1 &= f_1(X_1, X_2, \dots, X_N) \\ X_2 &= f_2(X_1, X_2, \dots, X_N) \\ &\vdots \\ X_N &= f_N(X_1, X_2, \dots, X_N) \end{aligned}$$

The **Functional** Approach for Inter-procedural Analysis

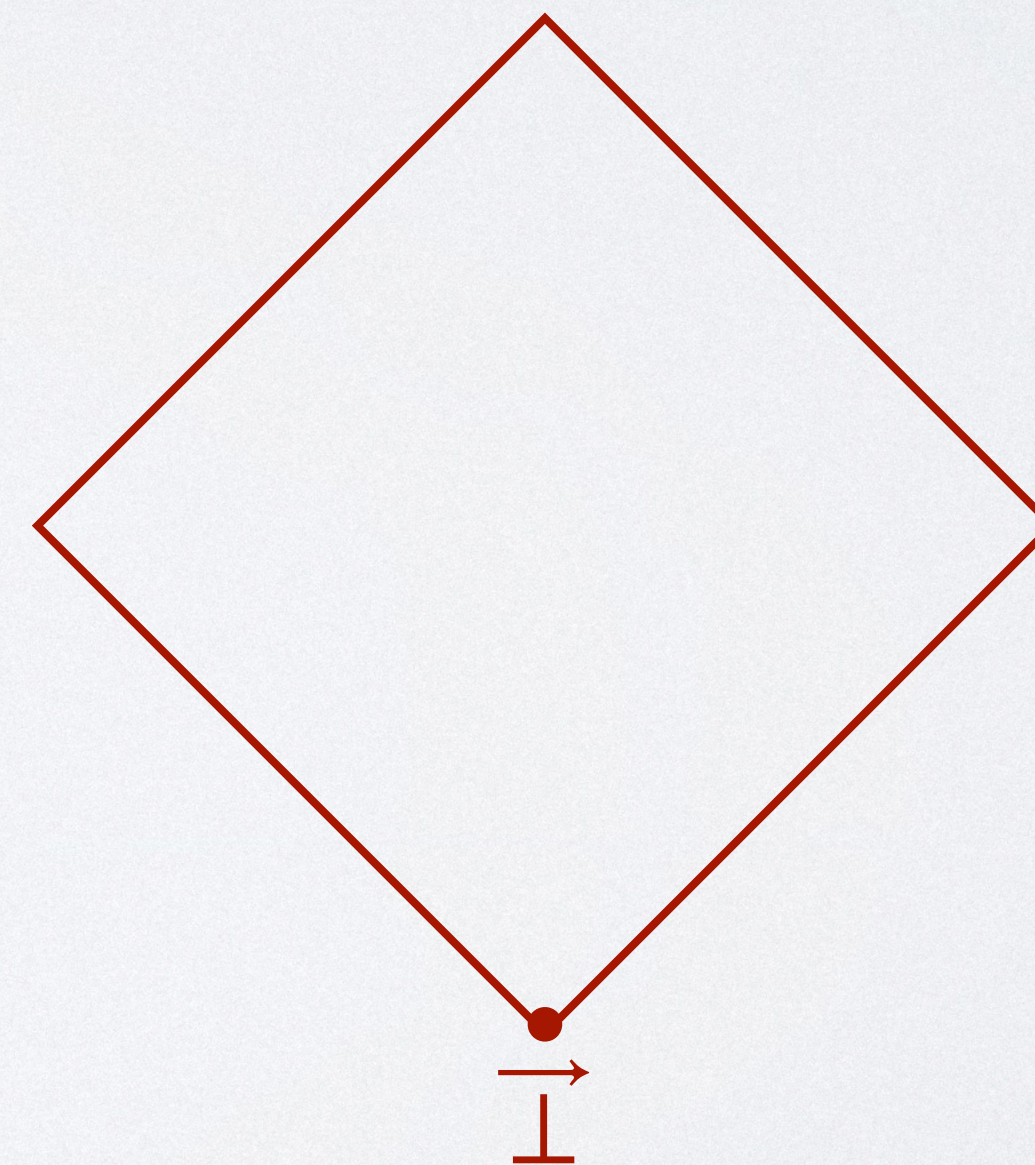
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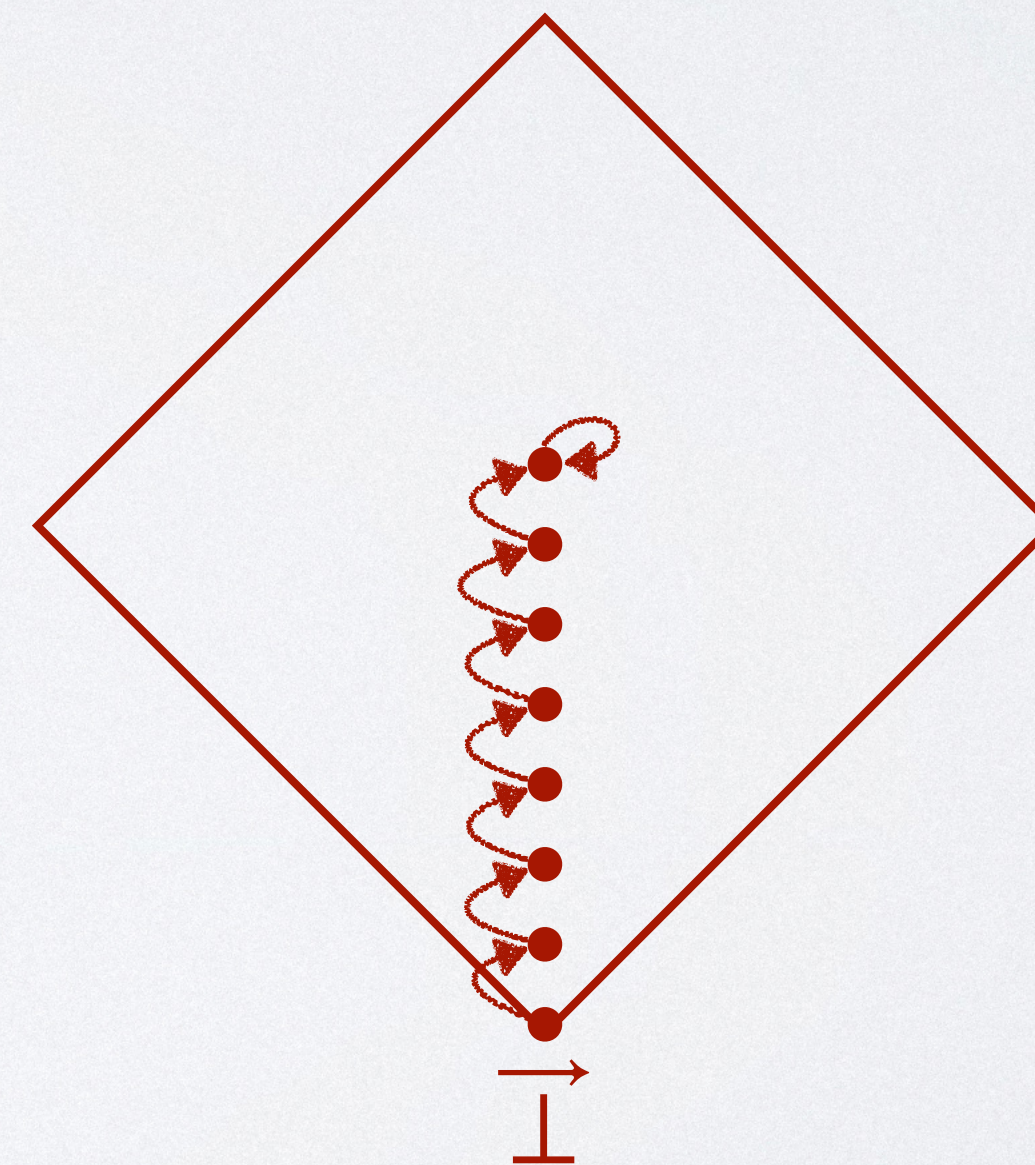
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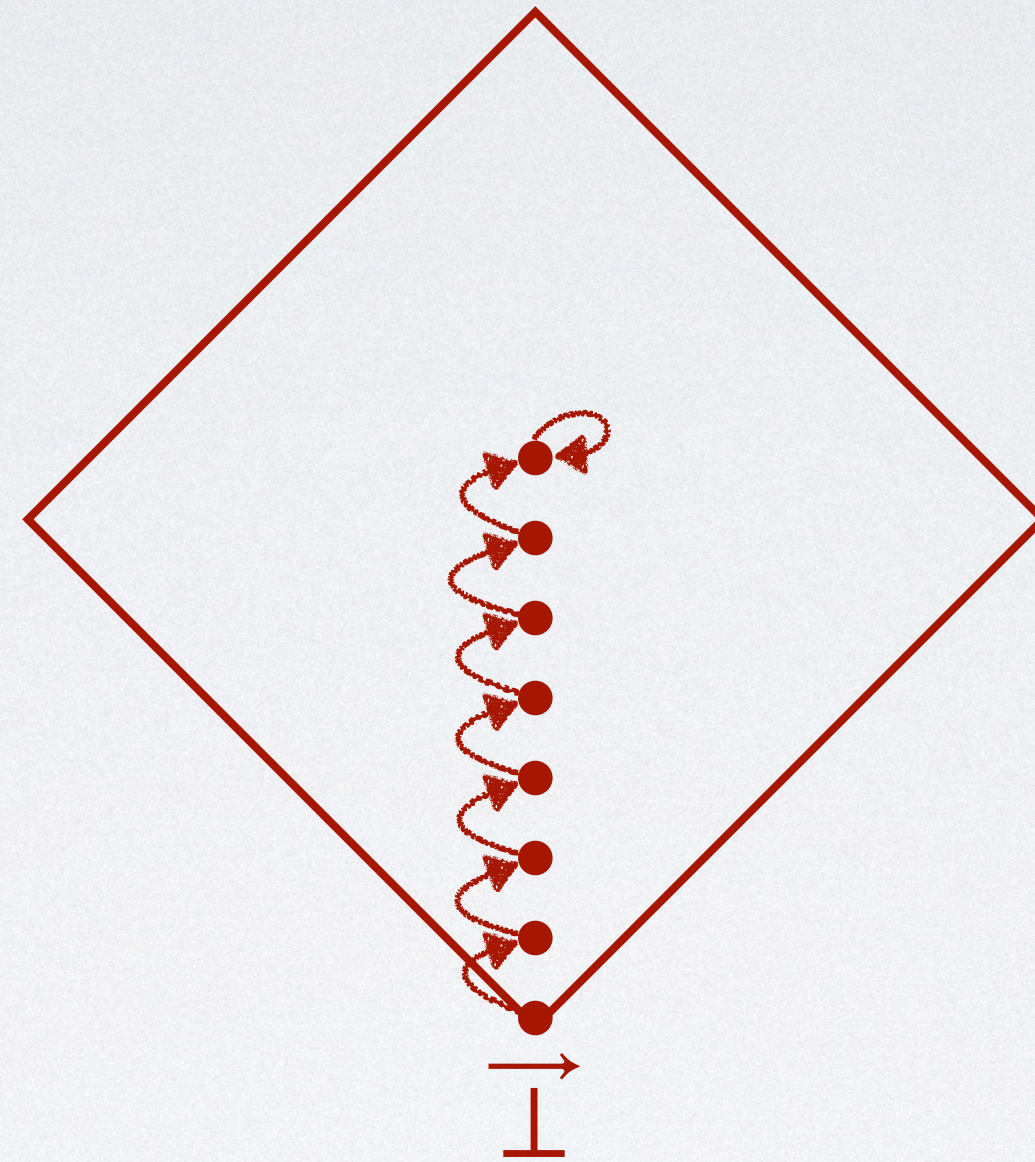


The **Newtonian** Approach for Inter-procedural Analysis

The **Newtonian** Approach for Inter-procedural Analysis

- **Kleene iteration**

$$\begin{aligned} \kappa^{(0)} &= \perp \\ \kappa^{(i+1)} &= f(\kappa^{(i)}) \end{aligned}$$



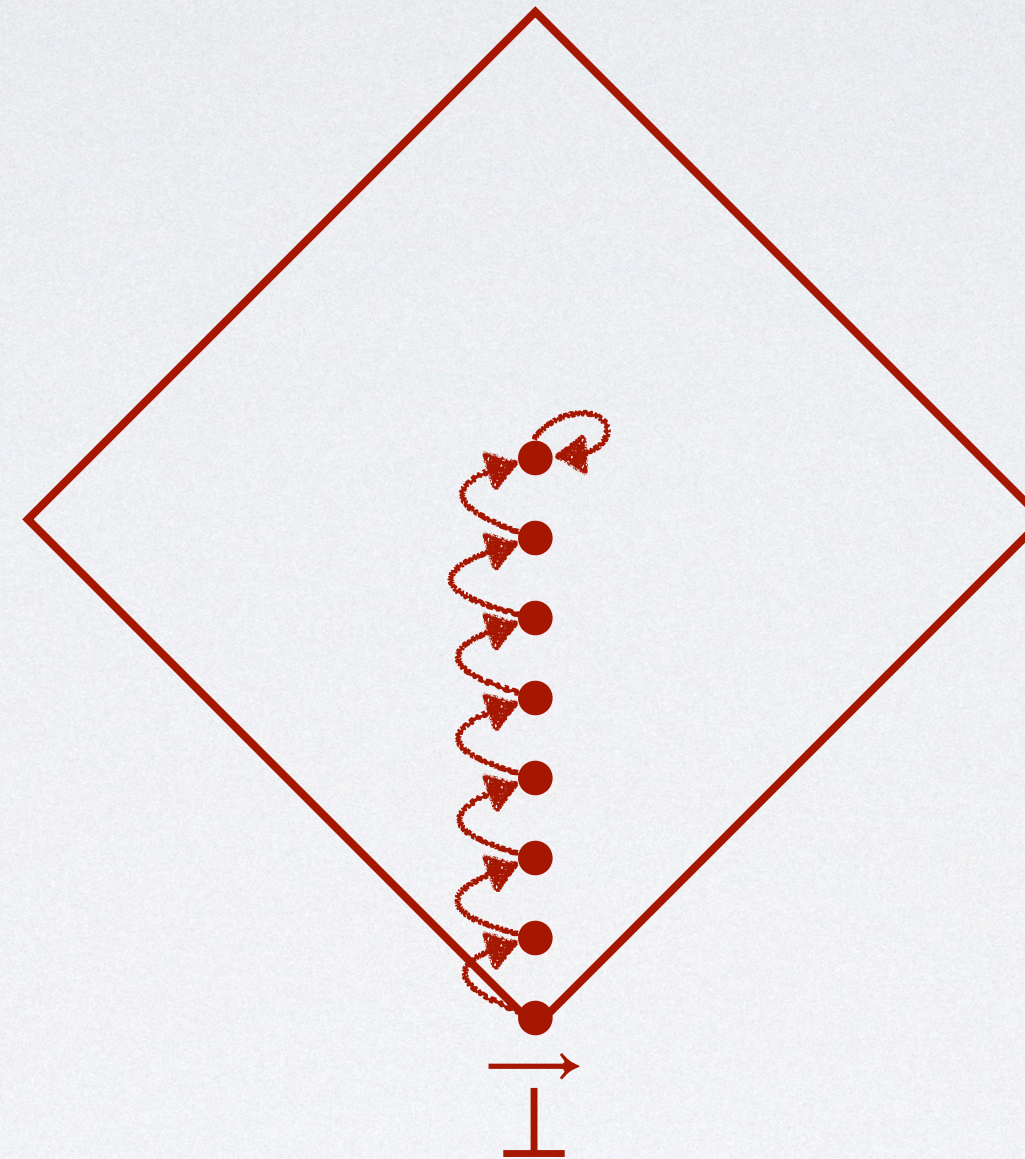
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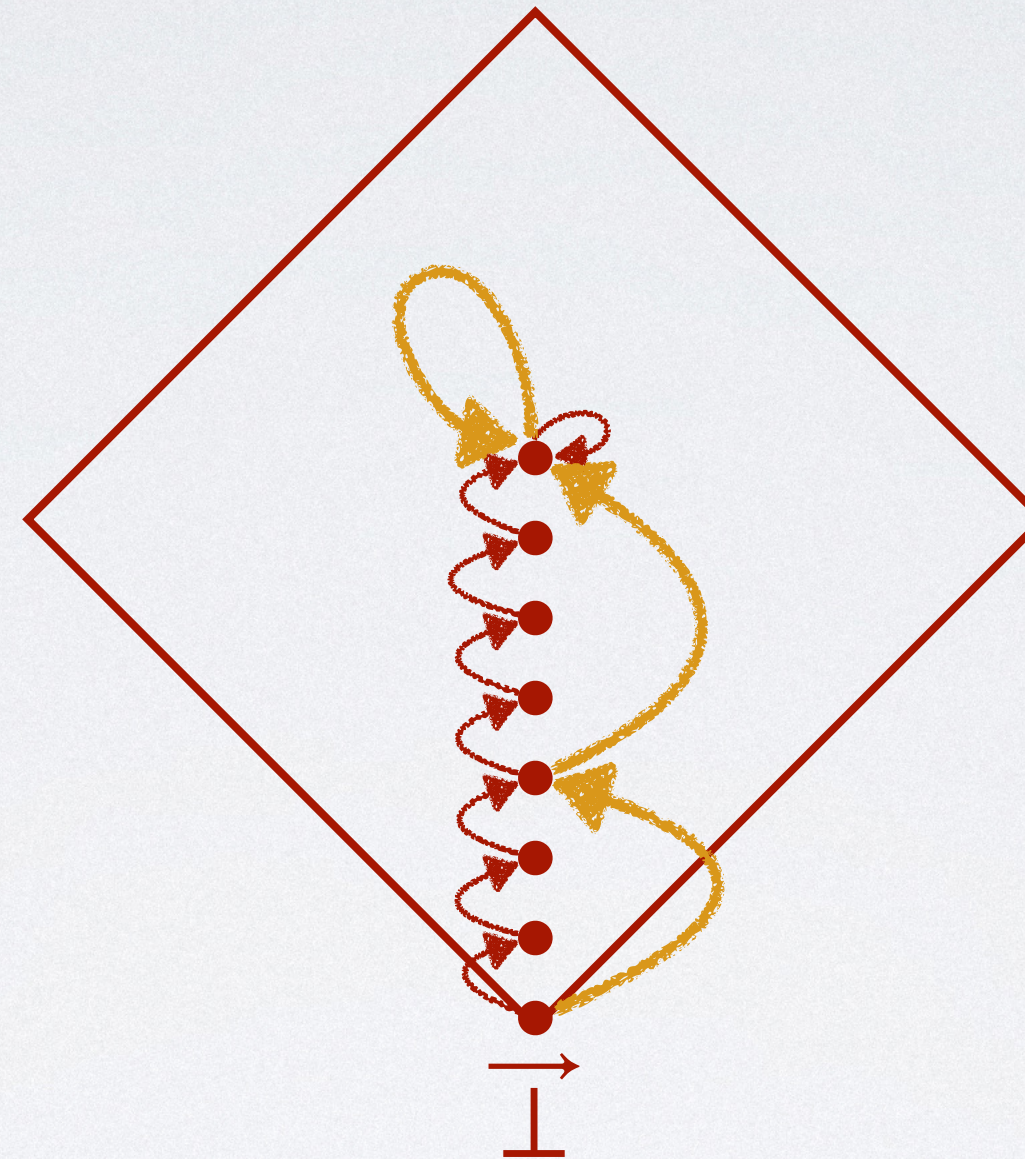
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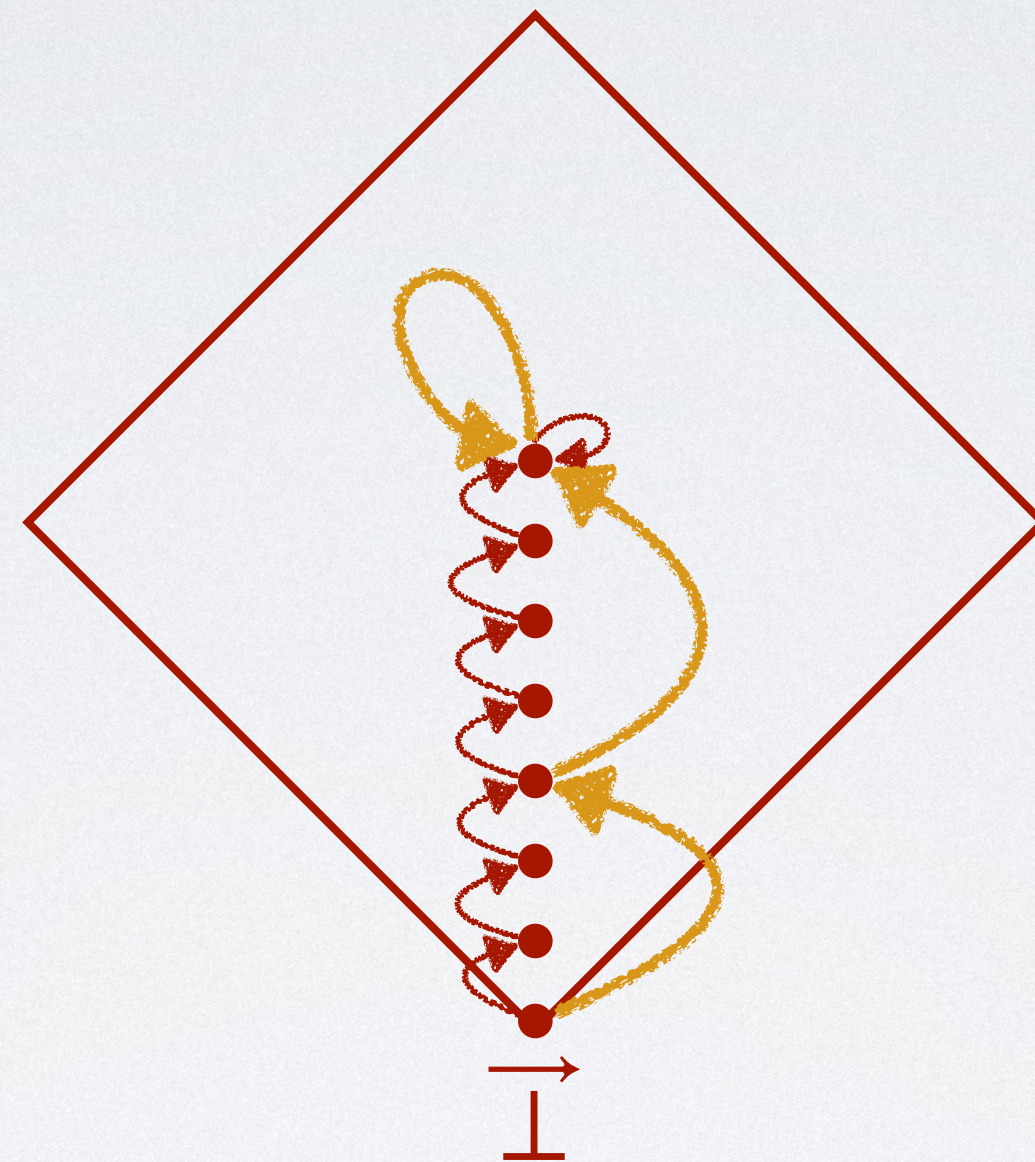
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What is this?



The **Newtonian** Approach for Inter-procedural Analysis

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proc X begin
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The **Newtonian** Approach for Inter-procedural Analysis

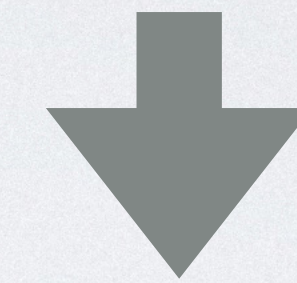
$$X = \mathbf{skip}_{1/3} \oplus (X \otimes X)$$

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Computing $\mathbb{P}[\text{terminate}]$

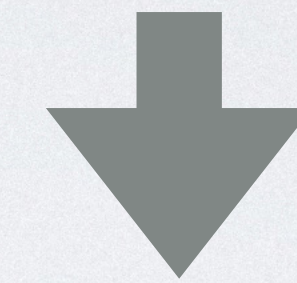
$$p = 1/3 * 1 + 2/3 * (p * p)$$

The **Newtonian** Approach for Inter-procedural Analysis

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Non-linear!



Computing $\mathbb{P}[\text{terminate}]$

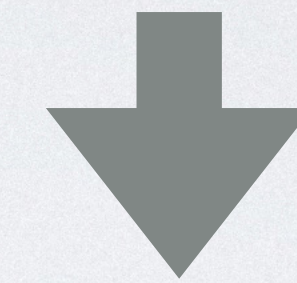
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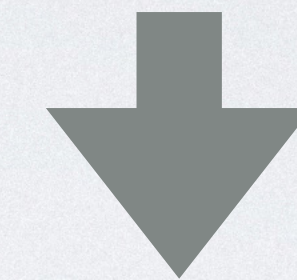
Newton's method

The **Newtonian** Approach for Inter-procedural Analysis

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end
```

$$X = \text{skip}_{1/3} \oplus (X \otimes X)$$

Non-linear!



Computing $\mathbb{P}[\text{terminate}]$

$$p = 1/3 * 1 + 2/3 * (p * p)$$

Newton's method

$$f(x) = 1/3 * 1 + 2/3 * (x * x)$$

The **Newtonian** Approach for Inter-procedural Analysis

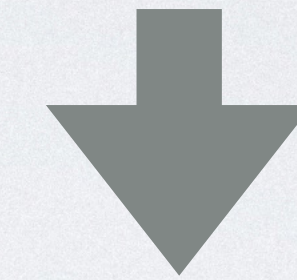
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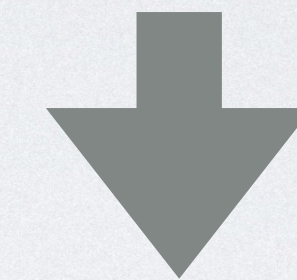
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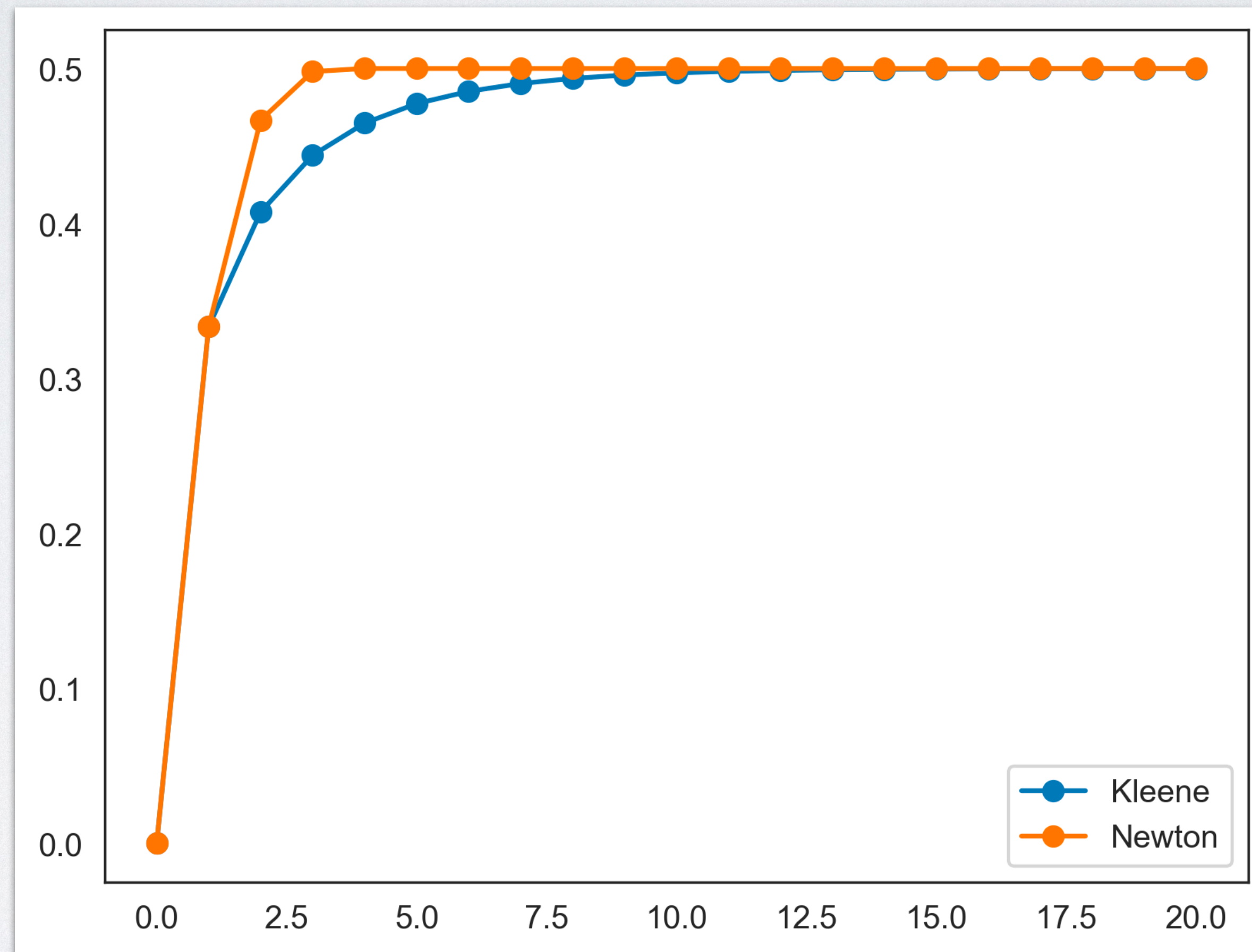
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Linear!

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Newton's Method Converges Faster





Newtonian Program Analysis for Probabilistic Programs



Newtonian Program Analysis for Probabilistic Programs

- Idea: Apply Newton's method to **algebraic structures**, e.g., Markov algebras

Newtonian Program Analysis for Probabilistic Programs

- Idea: Apply Newton's method to **algebraic structures**, e.g., Markov algebras
- Derive the **syntactic** differential of algebraic expressions

$$\mathcal{D}(X) \triangleq X$$

$$\mathcal{D}(f_\phi \oplus g) \triangleq \mathcal{D}f_\phi \oplus \mathcal{D}g$$

$$\mathcal{D}(f \otimes g) \triangleq (\mathcal{D}f \otimes g) \oplus (f \otimes \mathcal{D}g)$$

$$\mathcal{D}(f \sqcap g) \triangleq ((f \oplus \mathcal{D}f) \sqcap (g \oplus \mathcal{D}g)) \ominus (f \sqcap g)$$

Newtonian Program Analysis for Probabilistic Programs

- Idea: Apply Newton's method to **algebraic structures**, e.g., Markov algebras
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Procedure call to X

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Newtonian Program Analysis for Probabilistic Programs

- Idea: Apply Newton's method to **algebraic structures**, e.g., Markov algebras
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Branching

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Newtonian Program Analysis for Probabilistic Programs

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Sequencing

$$\mathcal{D}(f \otimes g) \triangleq (\mathcal{D}f \otimes g) \oplus (f \otimes \mathcal{D}g)$$

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Nondeterministic-
choice

Newtonian Program Analysis for Probabilistic Programs

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- Derive the **syntactic** differential of algebraic expressions

$$\begin{aligned}\mathcal{D}(X) &\triangleq X \\ \mathcal{D}(f \oplus g) &\triangleq \mathcal{D}f \oplus \mathcal{D}g \\ \mathcal{D}(f \otimes g) &\triangleq (\mathcal{D}f \otimes g) \oplus (f \otimes \mathcal{D}g) \\ \mathcal{D}(f \sqcap g) &\triangleq ((f \oplus \mathcal{D}f) \sqcap (g \oplus \mathcal{D}g)) \ominus (f \sqcap g)\end{aligned}$$

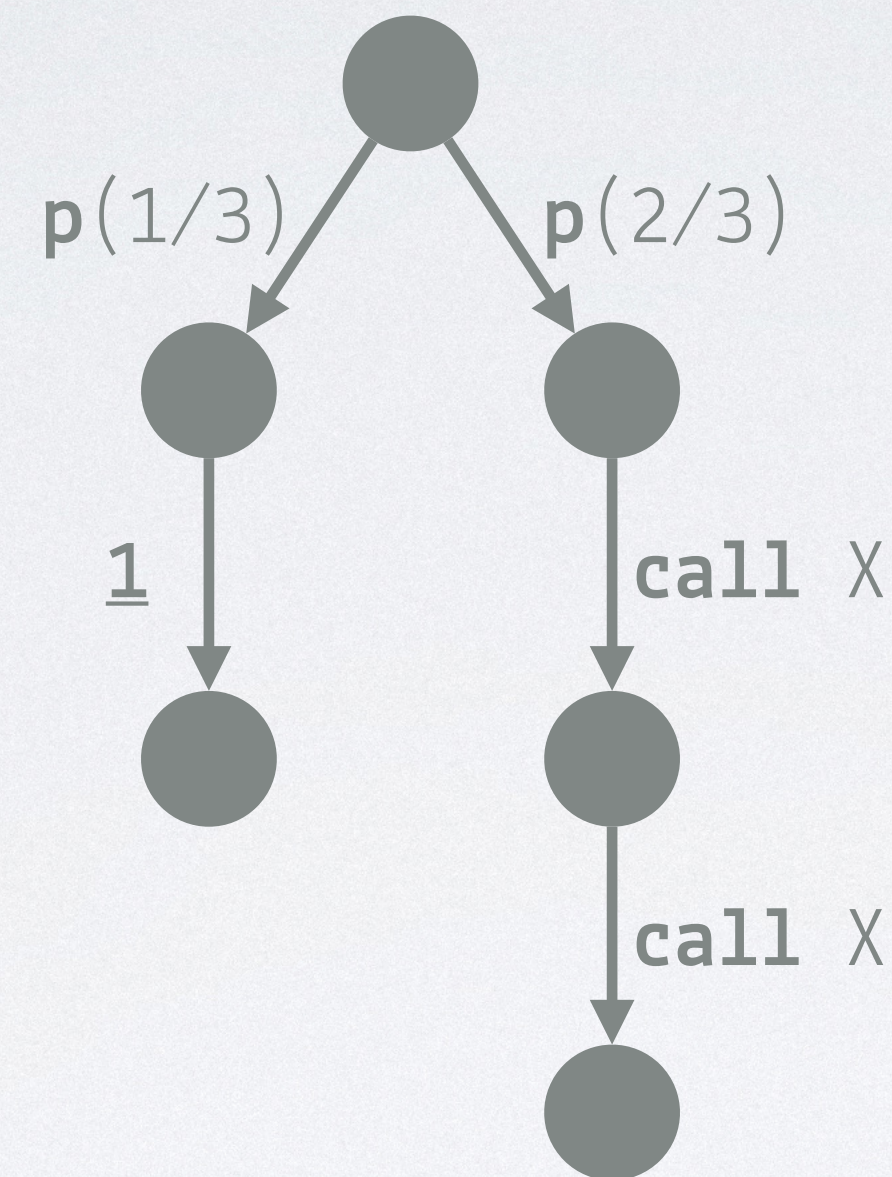
We change the structure from
 $\langle M, \sqsubseteq, \otimes, \oplus, \sqcap, \underline{0}, \underline{1} \rangle$
 to
 $\langle M, \oplus, \otimes, \oplus, \sqcap, \underline{0}, \underline{1} \rangle$
 to admit a partially-ordered
 semiring

Newtonian Program Analysis for Probabilistic Programs

```
proc X begin
  if prob(1/3) then
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  else
    call X;
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end
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Newtonian Program Analysis for Probabilistic Programs

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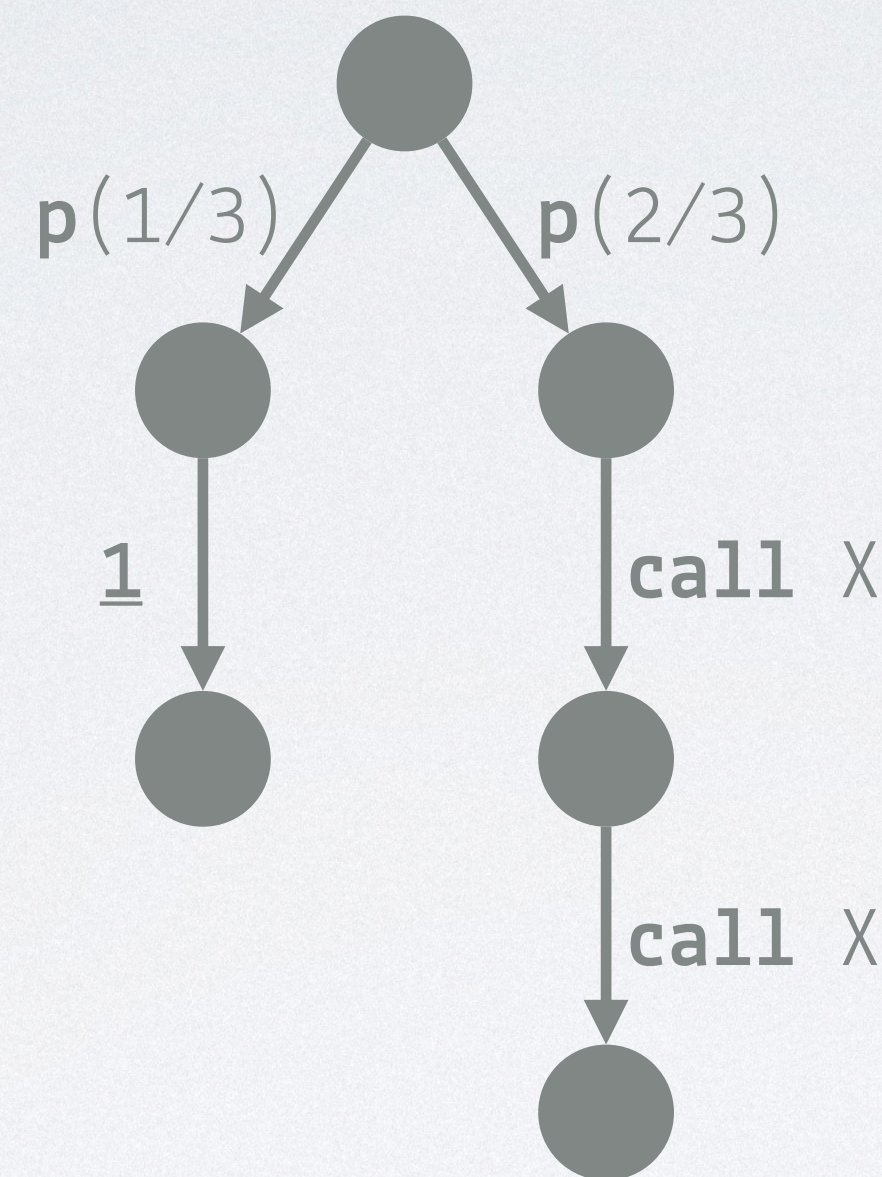


Newtonian Program Analysis for Probabilistic Programs

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```



$$X = f(X)$$

where

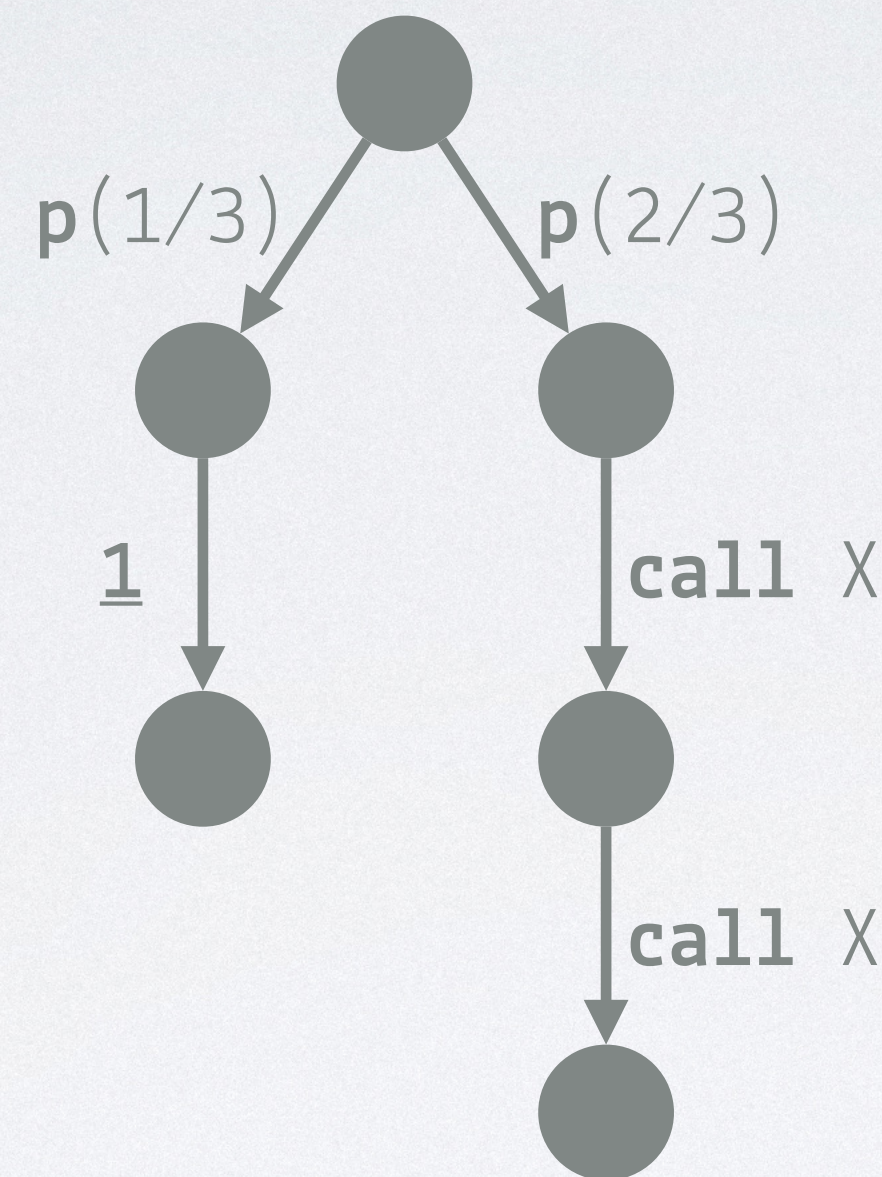
$$f(X) = (\text{skip} \otimes \underline{1})_{1/3} \oplus (X \otimes X \otimes \underline{1})$$

Newtonian Program Analysis for Probabilistic Programs

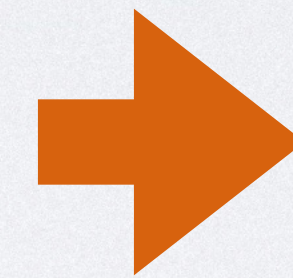
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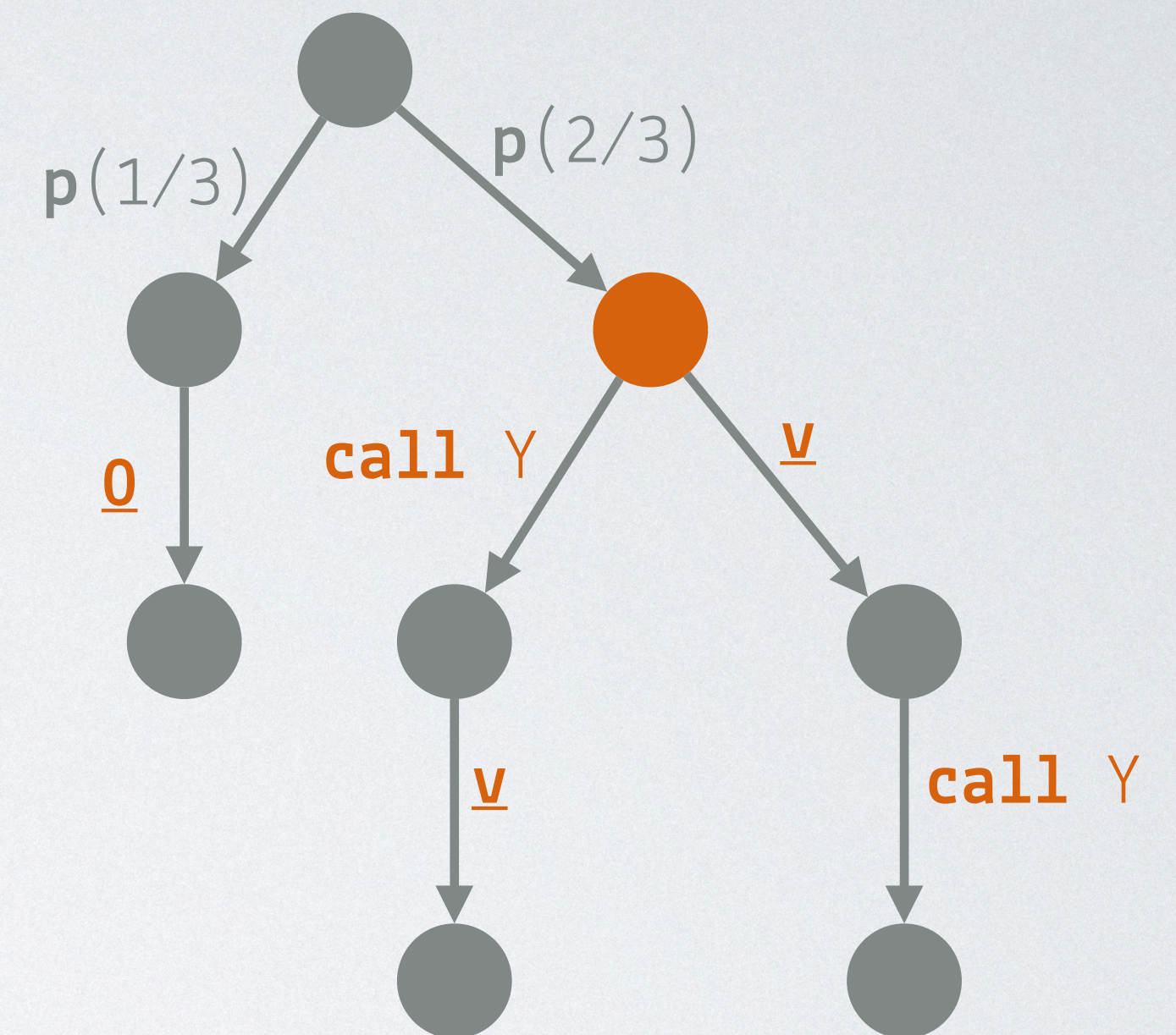
```



Differentiate



When $X = \underline{v}$



$$X = f(X)$$

where

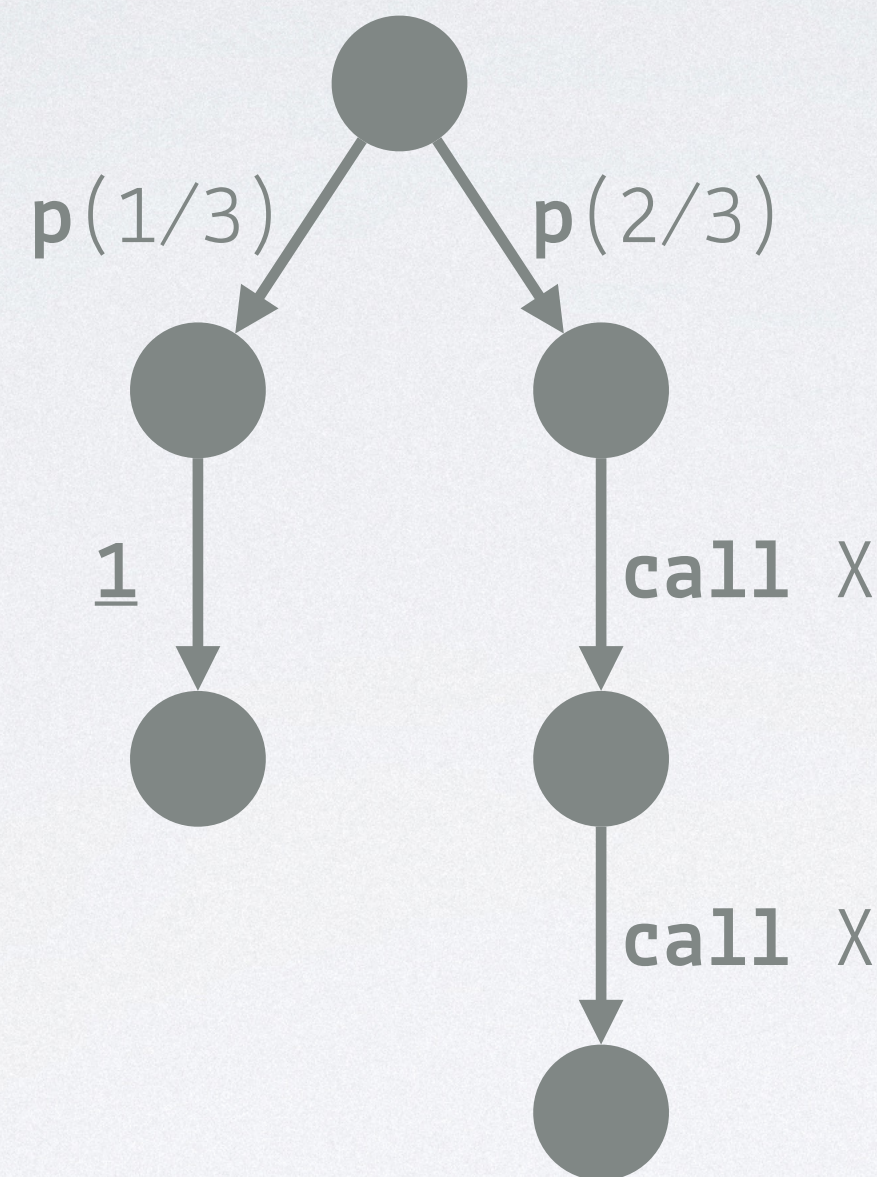
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Newtonian Program Analysis for Probabilistic Programs

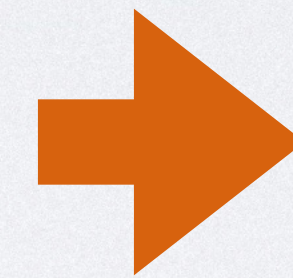
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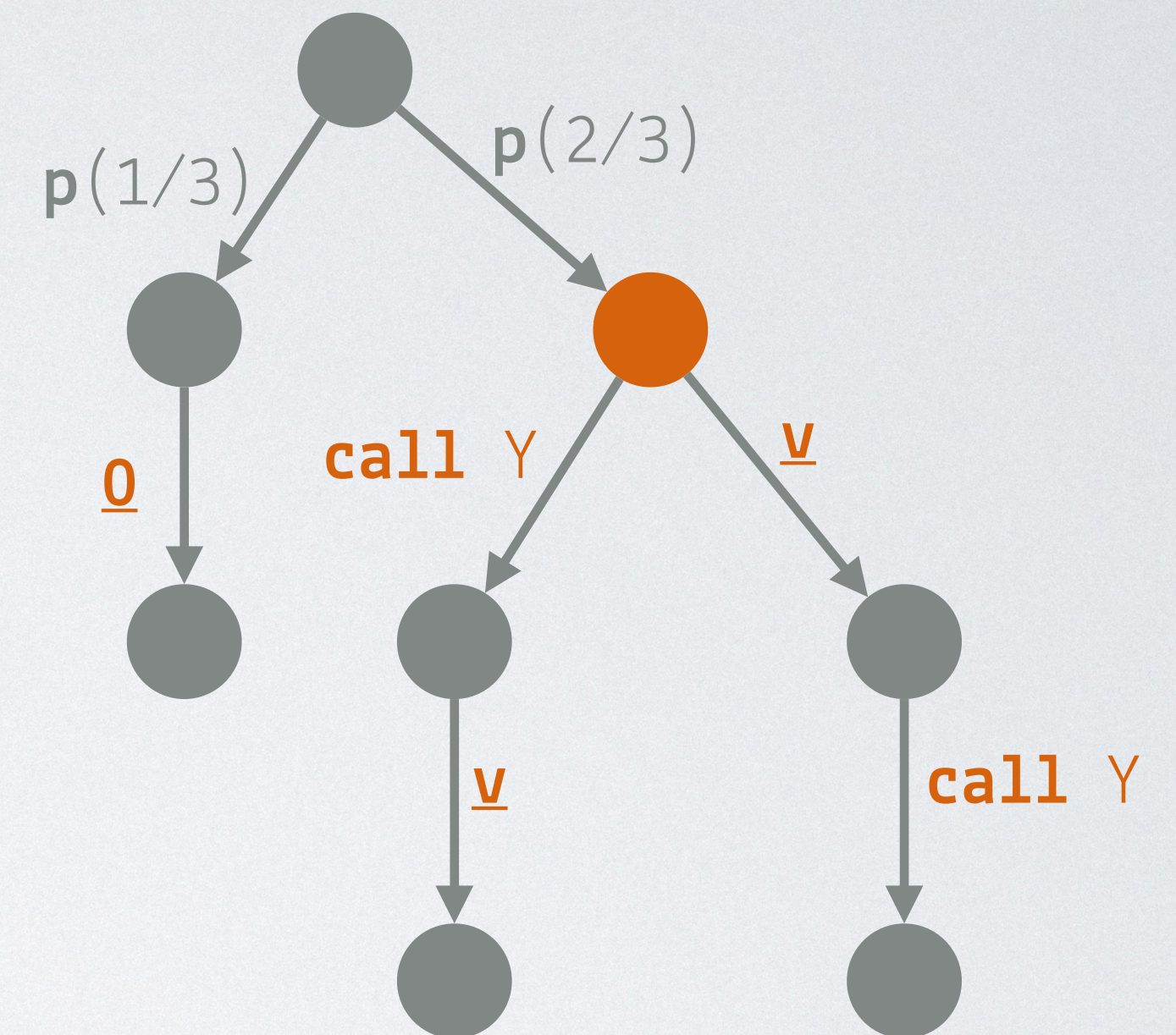
```



Differentiate



When $X = \underline{\nu}$



$$X = f(X)$$

where

$$f(X) = (\text{skip} \otimes \underline{1})_{1/3} \oplus (X \otimes X \otimes \underline{1})$$

$$Y = \delta \oplus (\underline{0}_{1/3} \oplus ((Y \otimes \nu) \oplus (\nu \otimes Y)))$$

where

$$\delta = f(\nu) \ominus \nu$$

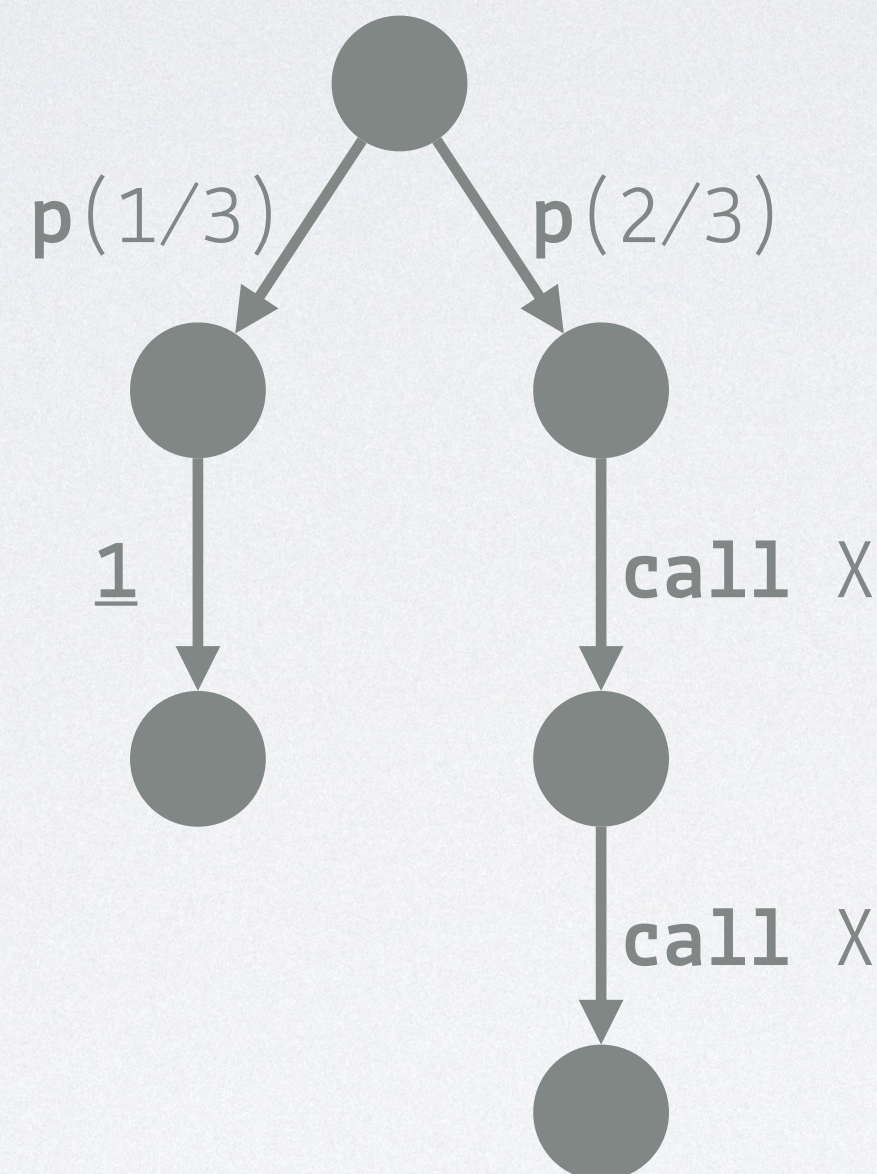
Newtonian Program Analysis for Probabilistic Programs

Every root-to-leaf path contains **at most one call**!

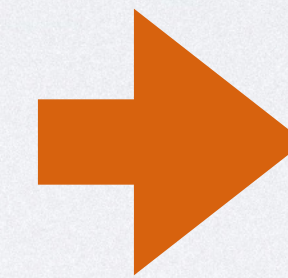
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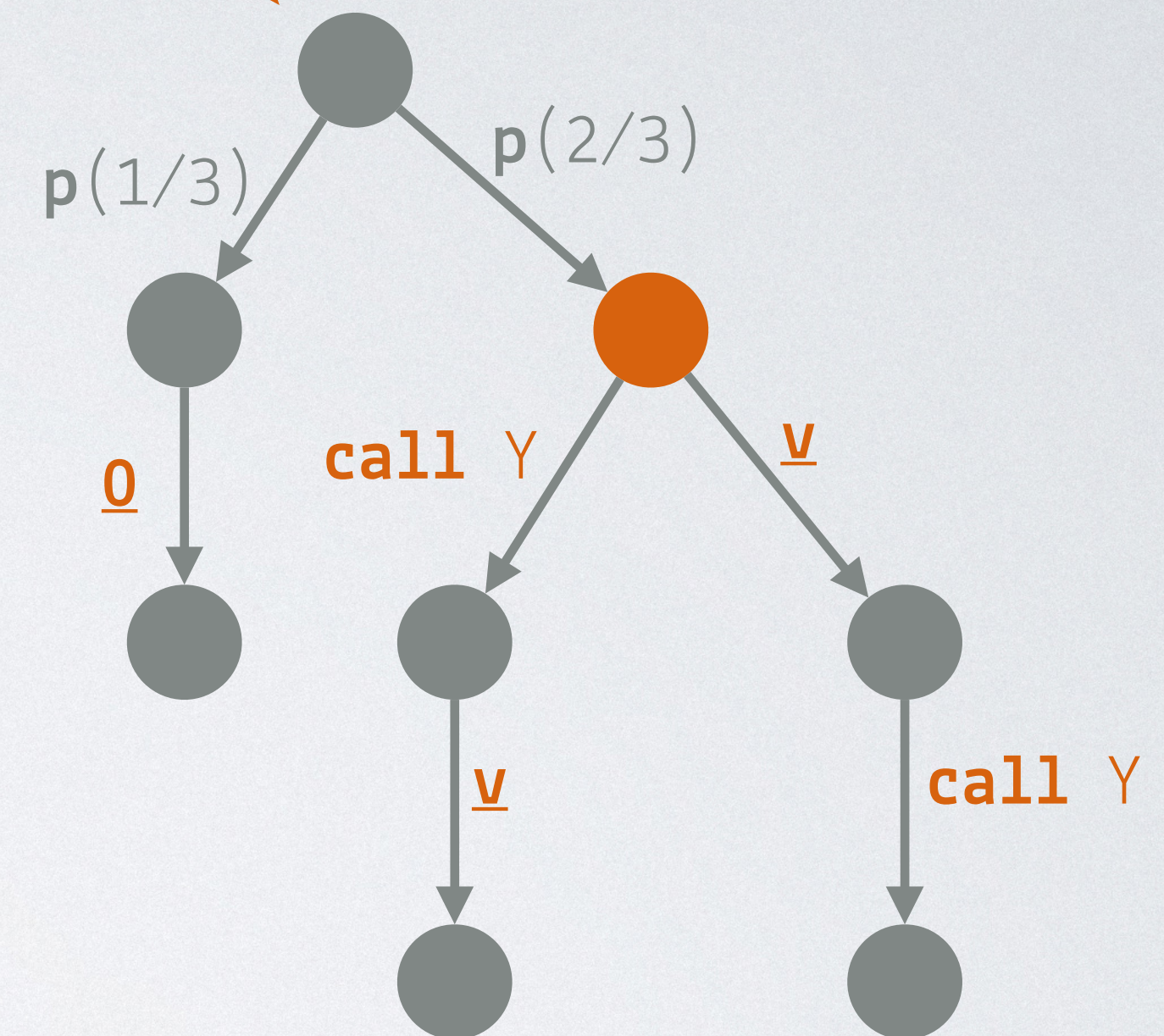
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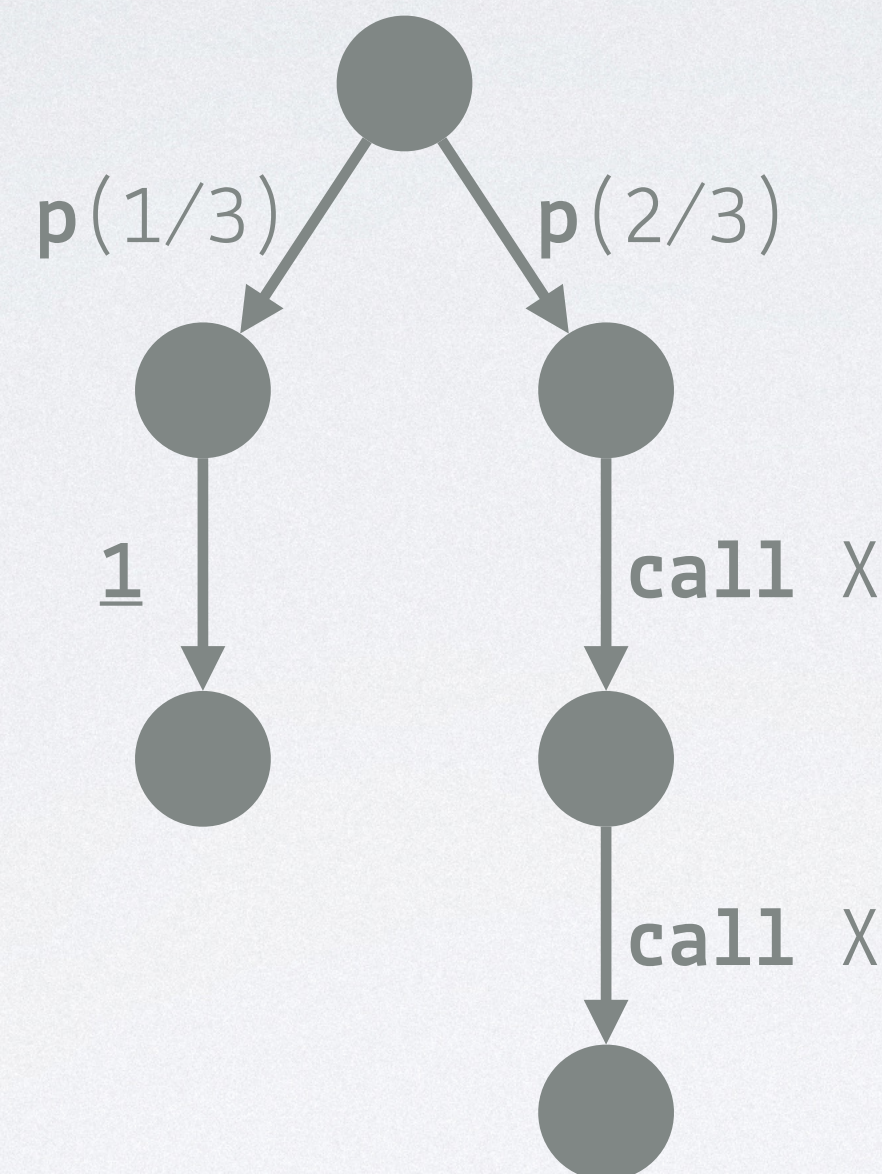
Newtonian Program Analysis for Probabilistic Programs

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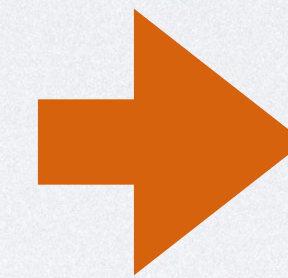
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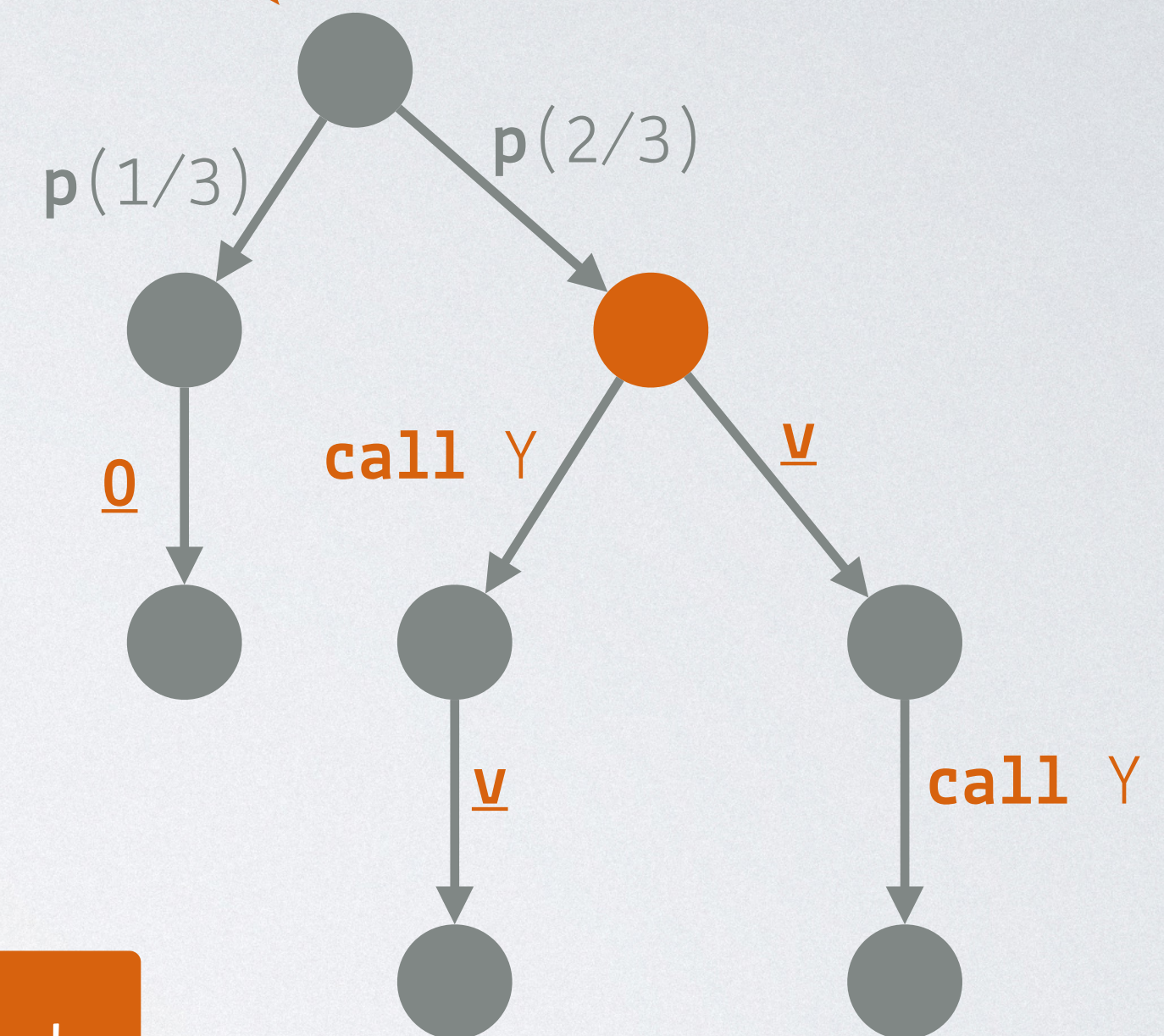
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Differentiate



When $X = \underline{\nu}$

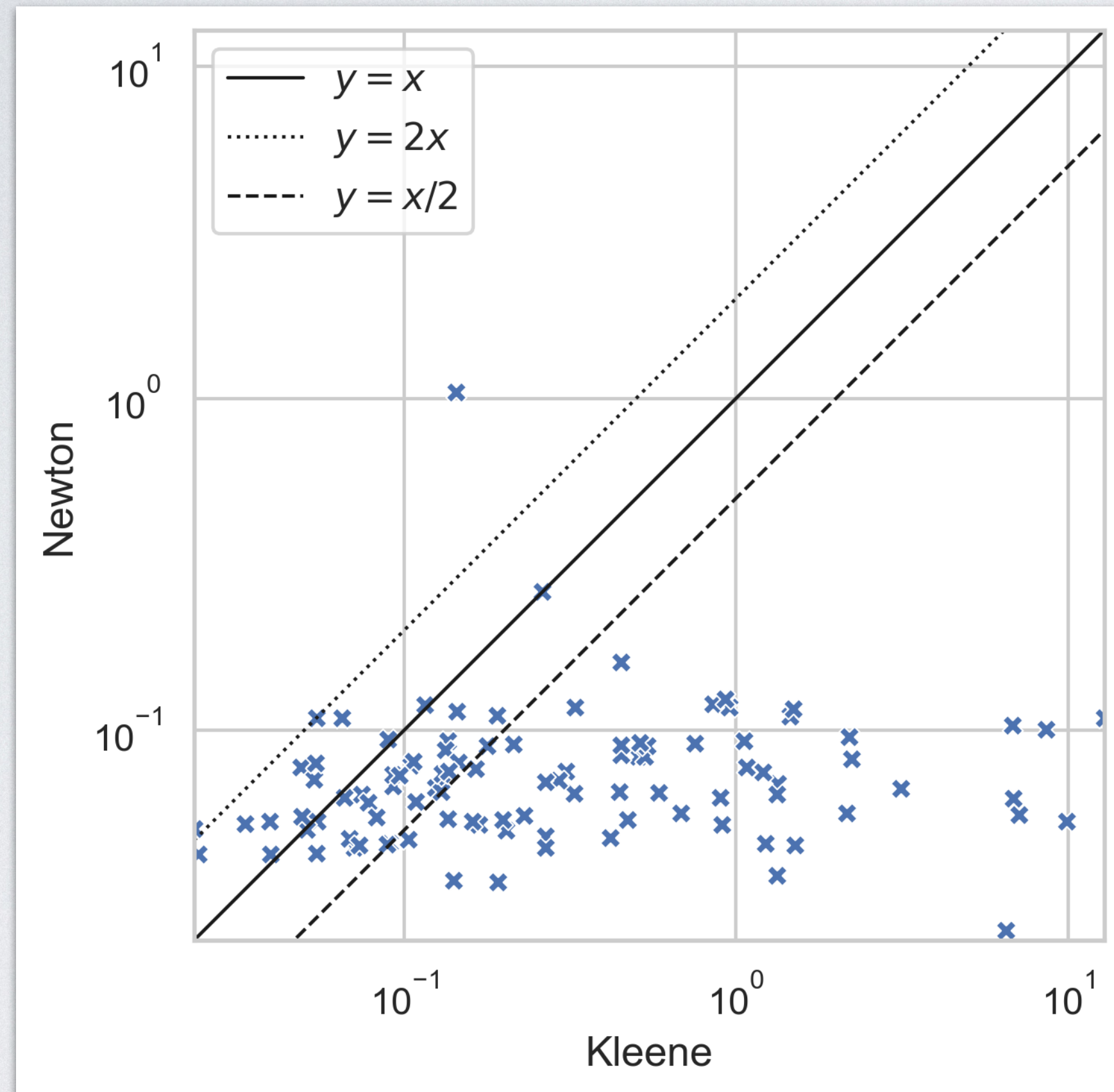


Linear!

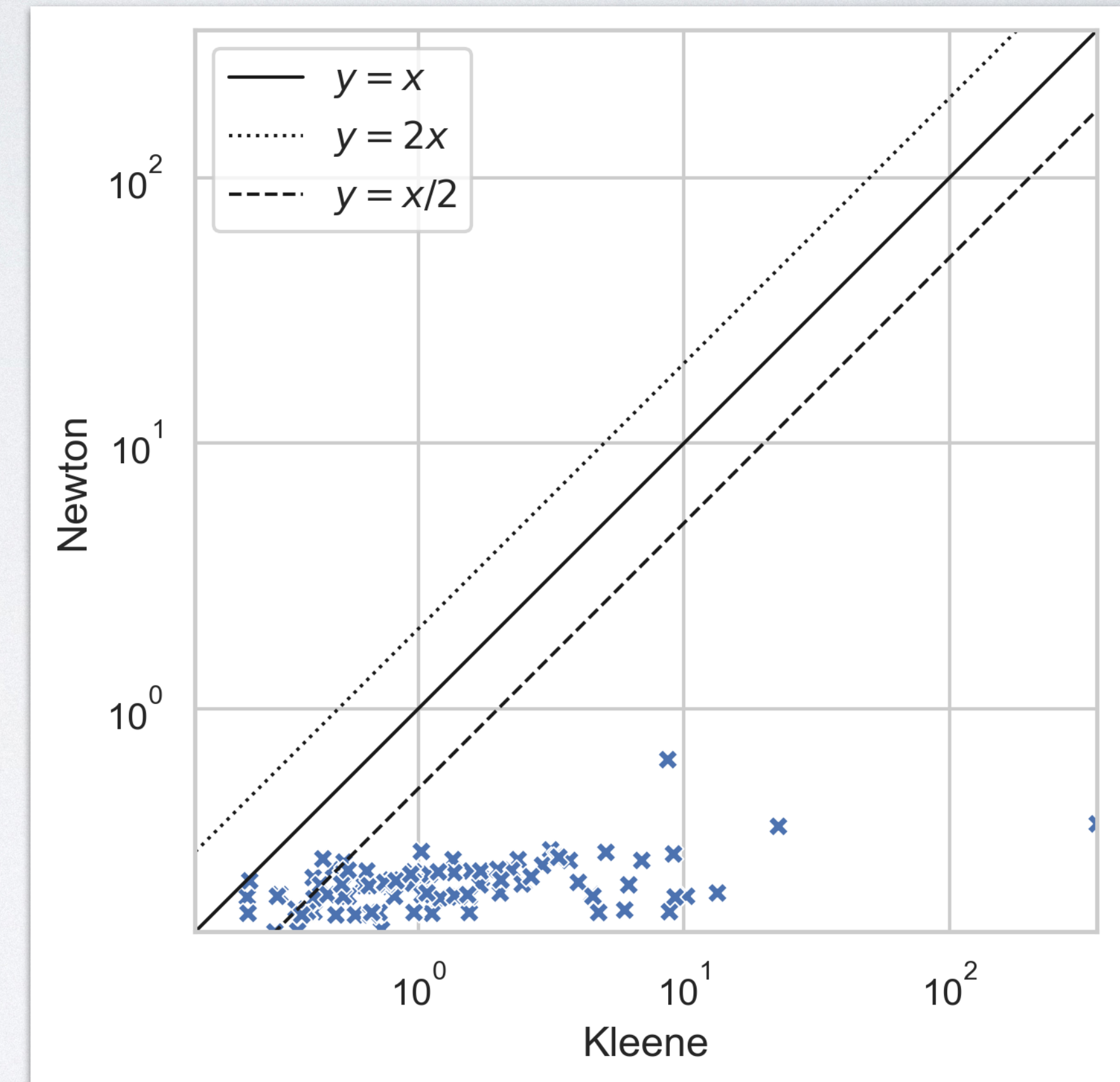
$$\begin{aligned}
 X &= f(X) \\
 \text{where} \\
 f(X) &= (\text{skip} \otimes \underline{1})_{1/3} \oplus (X \otimes X \otimes \underline{1})
 \end{aligned}$$

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 \text{where} \\
 \delta &= f(\nu) \ominus \nu
 \end{aligned}$$

Case Studies (Selected)



Termination-probability Analysis



Moment-of-reward Analysis

Our Papers

- Di Wang, Jan Hoffmann, Thomas Reps (2018). **PMAF: An Algebraic Framework for Static Analysis of Probabilistic Programs**. In *PLDI'18*.
- Di Wang, Jan Hoffmann, Thomas Reps (2019). **A Denotational Semantics for Low-Level Probabilistic Programs with Nondeterminism**. In *MFPS'19*.
- Di Wang, Thomas Reps (2024). **Newtonian Program Analysis of Probabilistic Programs**. In *OOPSLA'24*.

Towards a **flexible** and **efficient** framework for program analysis of probabilistic programs

- ☒ **Semantics:** Markov Algebras for Multiple Kinds of Confluences
- ☒ **Structure:** Construction of Recursive Program Schemes
- ☒ **Algorithm:** Newton's Method for Markov Algebras